



Laboratoire
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Beyond Decisiveness: When Statistical Verification Meets Numerical Verification

Benoît Barbot (LACL), Patricia Bouyer (LMF),
Serge Haddad (LMF)

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(submitted, not yet on ArXiv)

Purpose of this work

Design algorithms to estimate probabilities in some **infinite-state** Markov chains, **with guarantees**

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Our contributions

- ▶ Review two existing approaches (approximation algorithm and estimation algorithm) and specify the required hypothesis for correctness
- ▶ Propose an approach based on **importance sampling** and **abstraction** to partly relax the hypothesis
- ▶ Analyze empirically the approaches

Discrete-time Markov chains

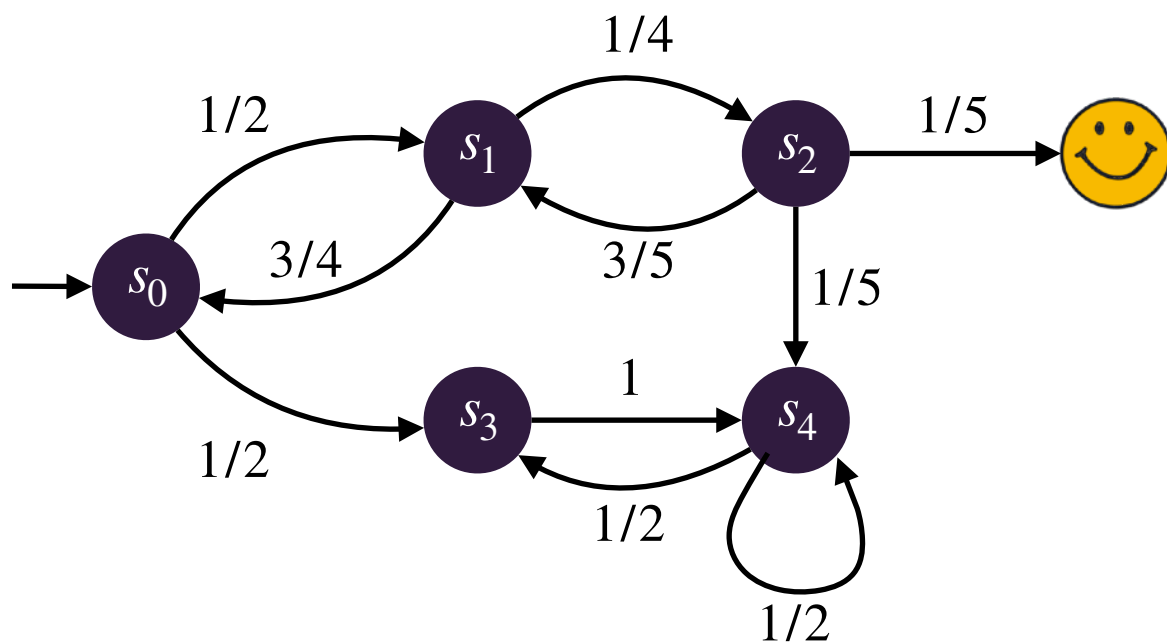
Discrete-time Markov chain (DTMC)

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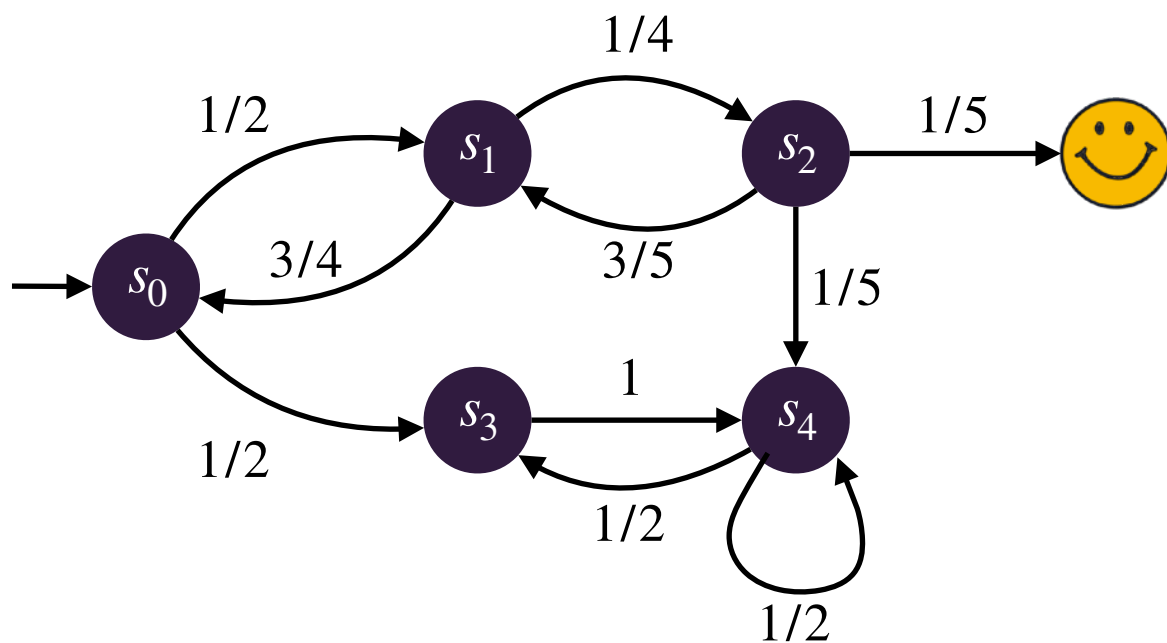


Finite Markov chain

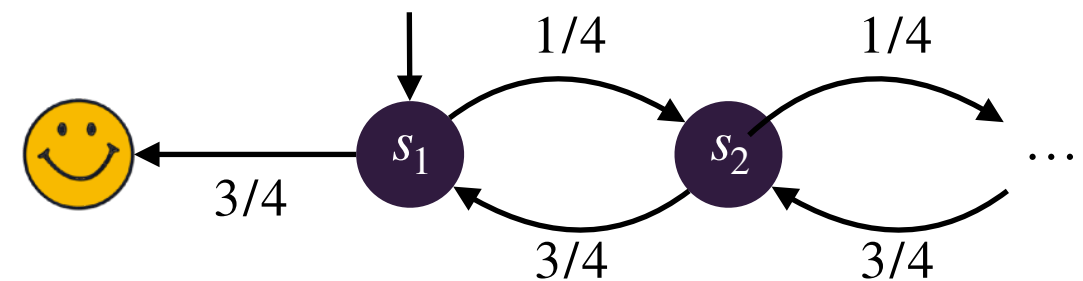
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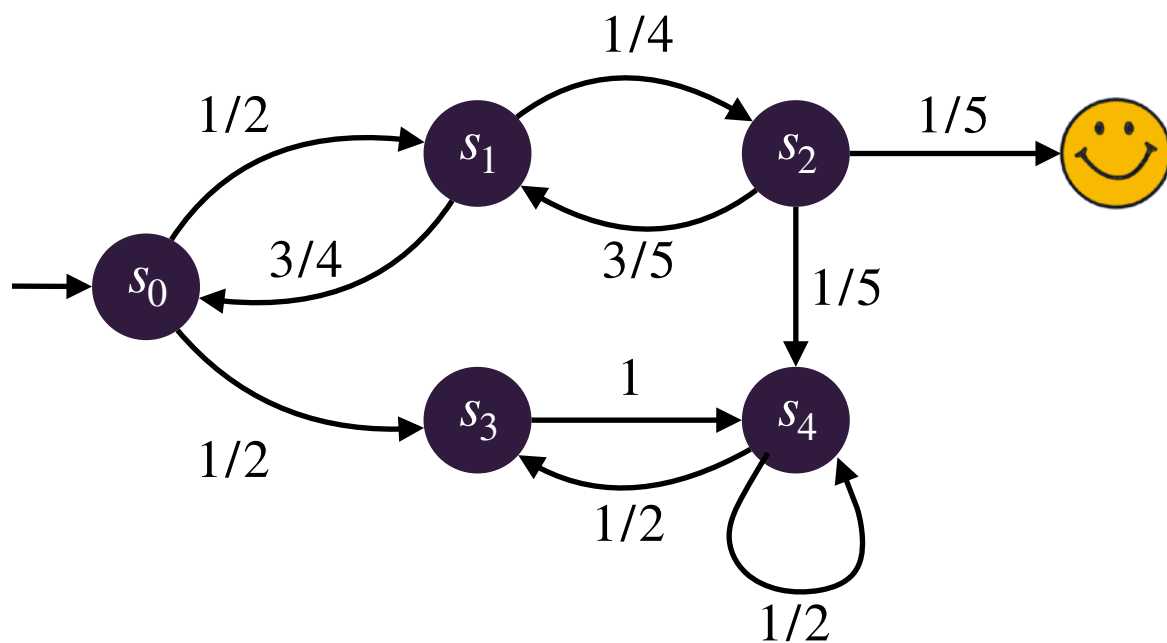
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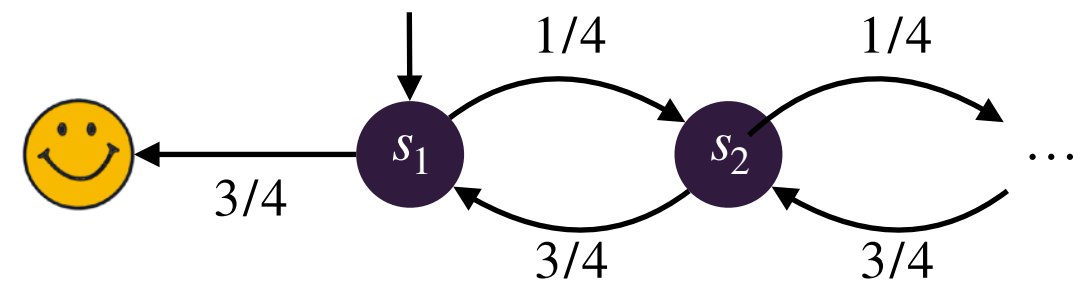
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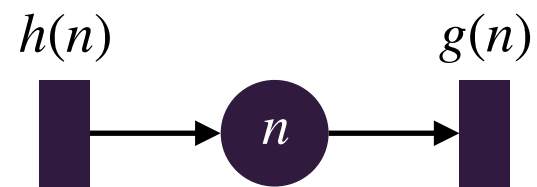
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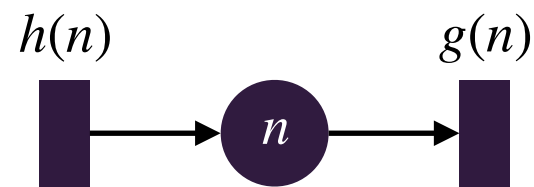
High-level models for (infinite) Markov chains

- ▶ Queues



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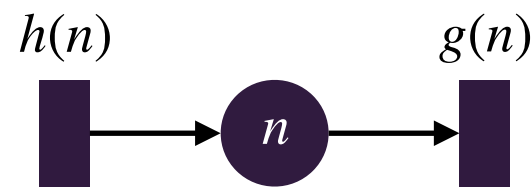
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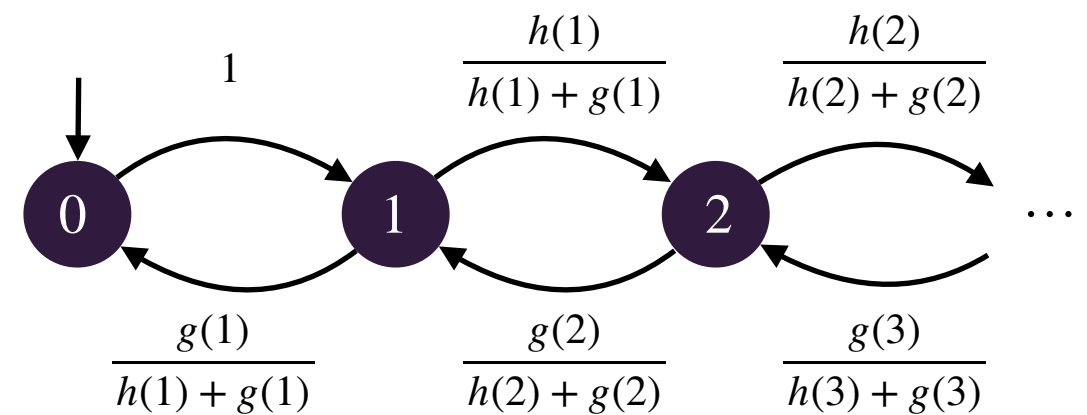
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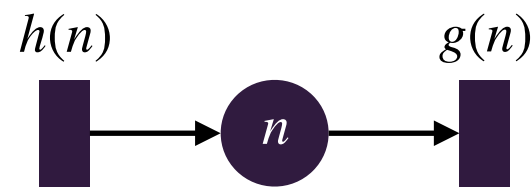


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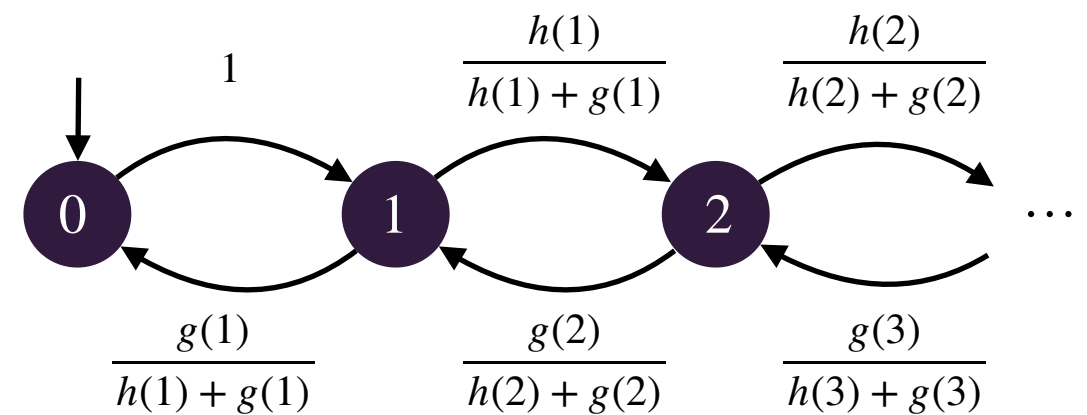


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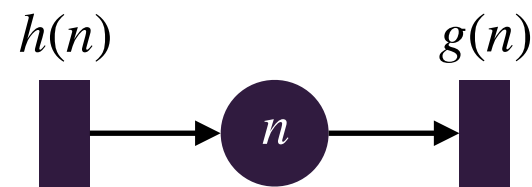


► Probabilistic pushdown automata

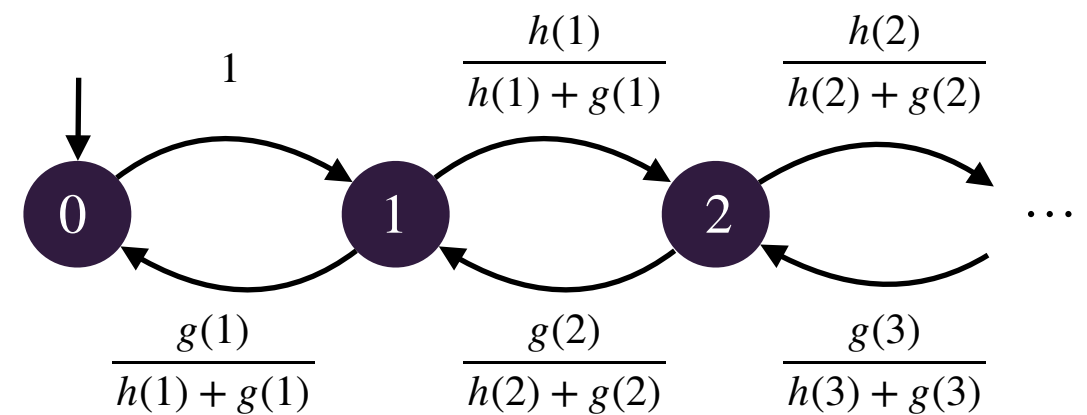
$$\begin{array}{lll} A \xrightarrow{1} C & A \xrightarrow{n} BB & B \xrightarrow{5} \varepsilon \\ B \xrightarrow{n} AA & C \xrightarrow{1} C & \end{array}$$

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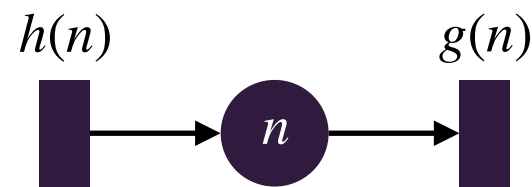
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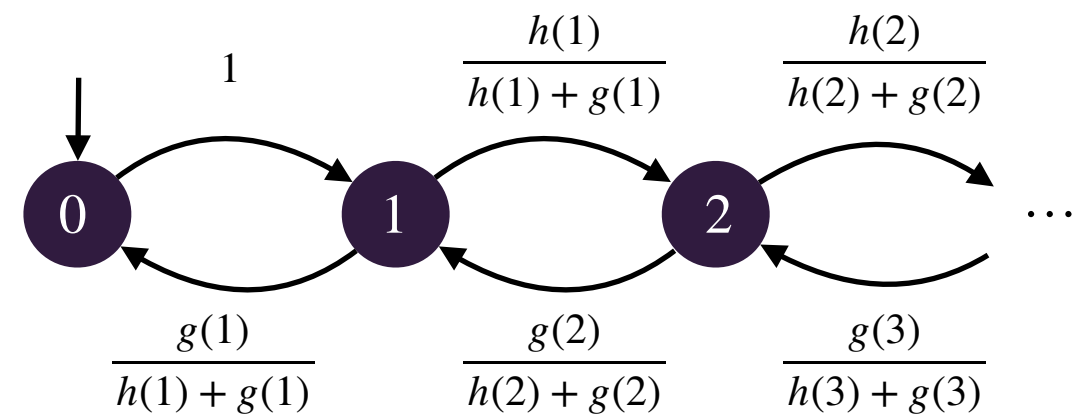
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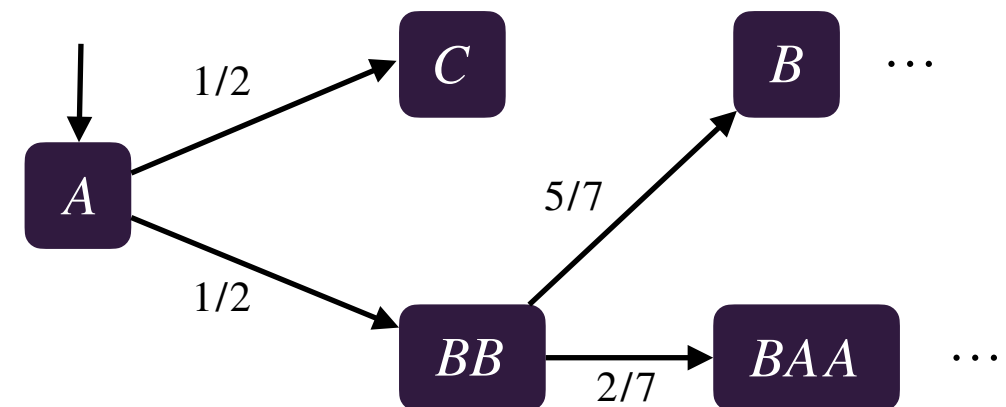
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Null recurrent if $p = 1/2$
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- ▶ Specific approaches for **decisive** Markov chains

Decisiveness

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A DTMC $\mathcal{C}$ is **decisive** from s w.r.t. ☺️ if $\mathbb{P}_s(\mathbf{F} \text{☺️} \vee \mathbf{F} \text{☹️}) = 1$

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- ▶ Examples of decisive Markov chains: finite Markov chains, probabilistic lossy channel systems, probabilistic VASS, noisy Turing machines, ...

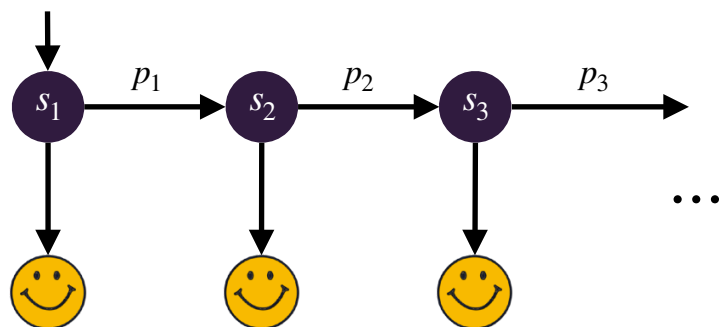
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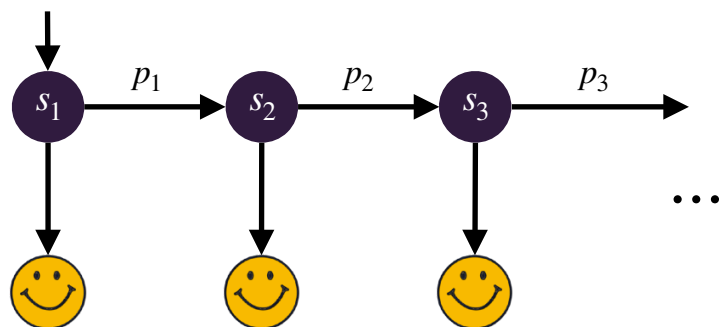
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$$\bullet \quad \mathbb{P}(\mathbf{G} \neg \text{☺️}) = \prod_{i \geq 1} p_i$$

- Decisive iff this product equals 0

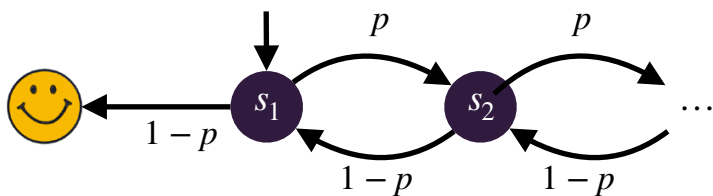
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- Recurrent random walk ($p \leq 1/2$): decisive
- Transient random walk ($p > 1/2$): not decisive

Deciding decisiveness?

Classes where decisiveness can be decided

- ▶ Probabilistic pushdown automata with constant weights [ABM07]
- ▶ Random walks with polynomial weights [FHY23]
- ▶ So-called probabilistic homogeneous one-counter machines with polynomial weights (this extends the model of quasi-birth death processes) [FHY23]

Approximation scheme

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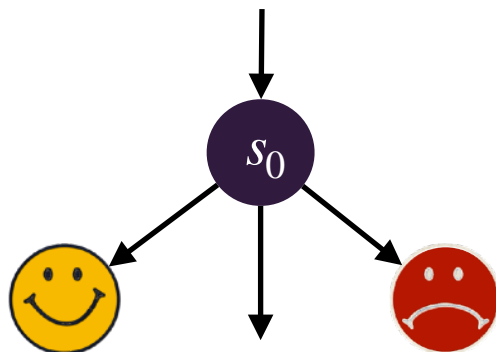
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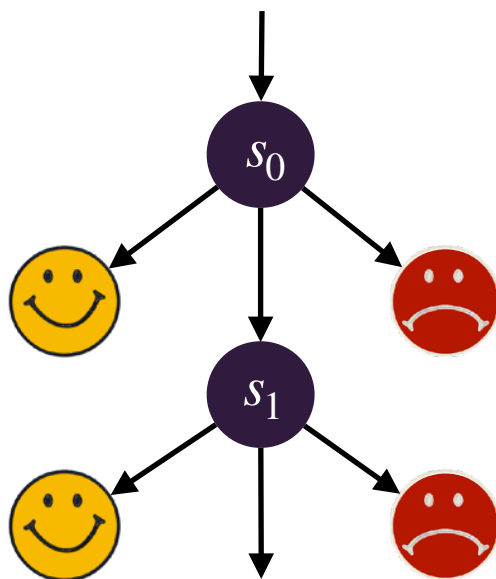
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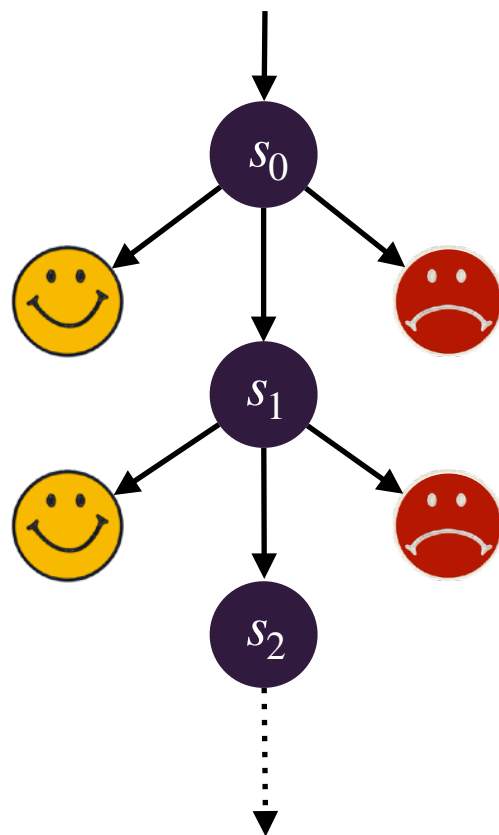
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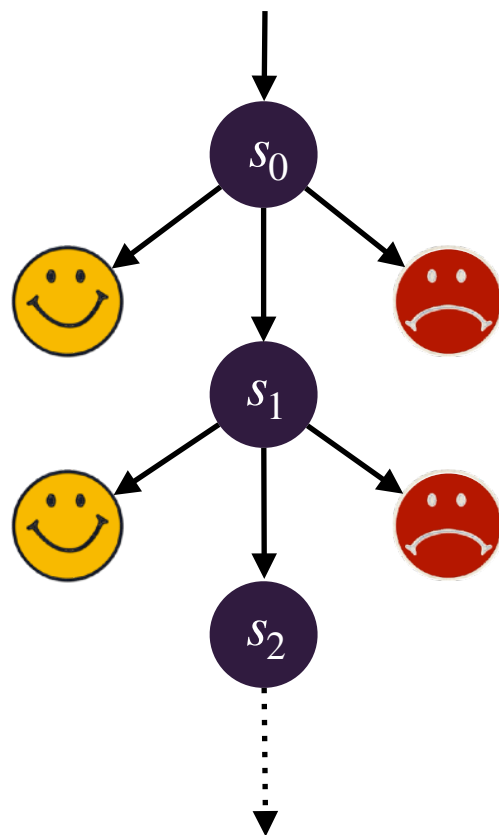
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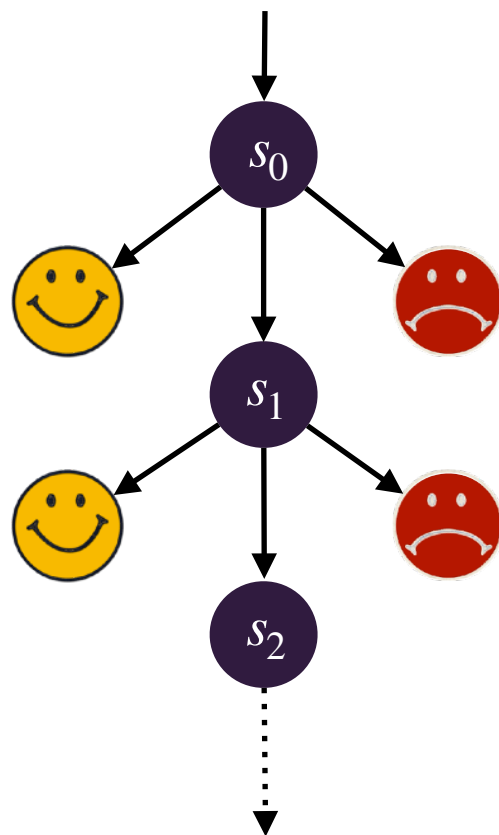
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Does it converge?

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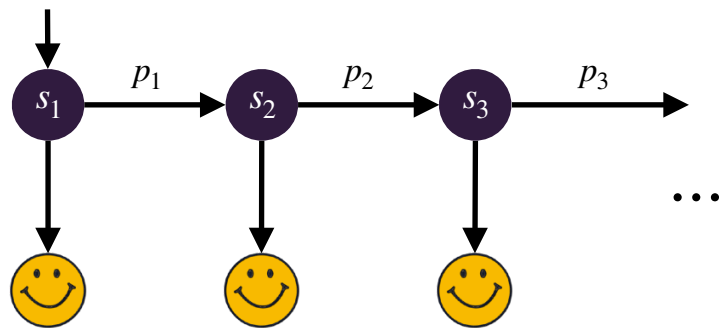
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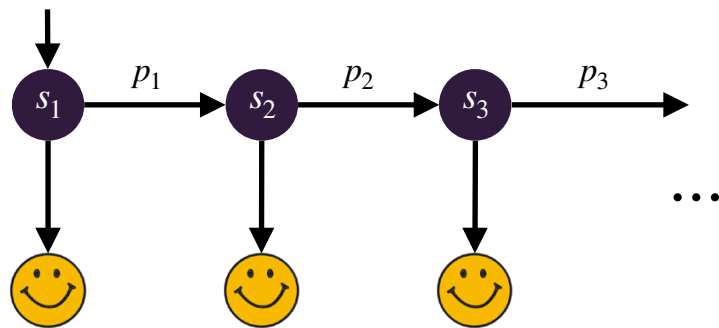
$$\lim_{n \rightarrow \infty} p_n^{\text{yes}} = \mathbb{P}(\mathbf{F} \text{ 😊})$$

Non-converging example



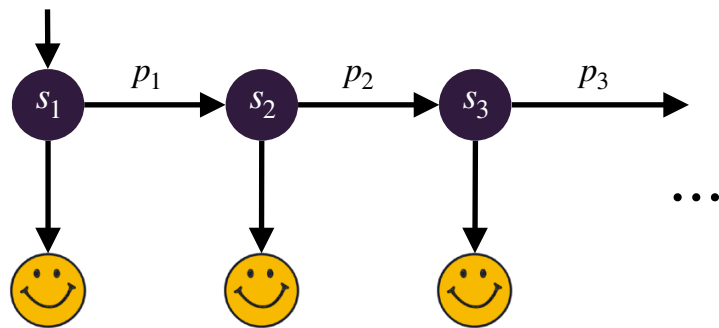
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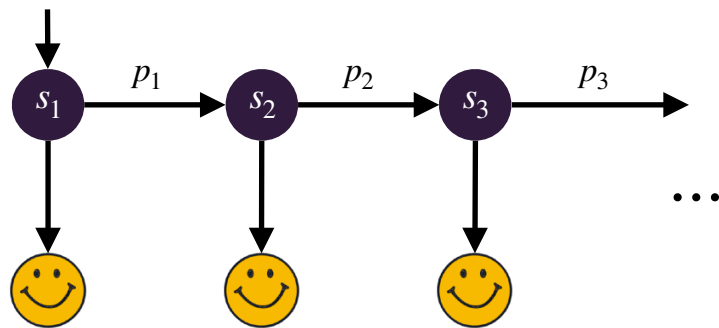
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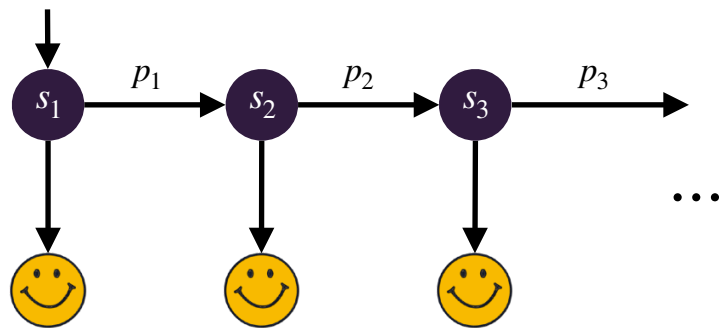


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► $\lim_{n \rightarrow +\infty} p_n^{\text{yes}} = \mathbb{P}(\mathbf{F} \text{ }) < 1$

Non-converging example



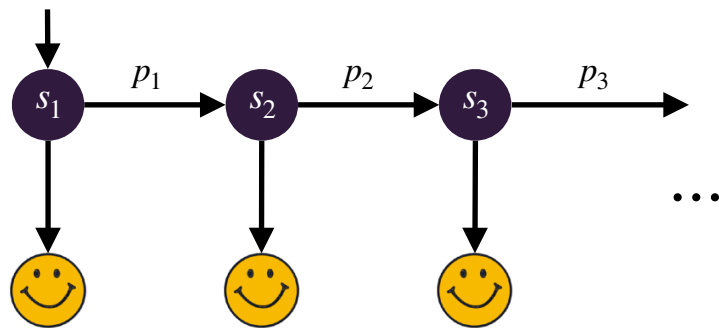
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The approximation scheme
does not converge

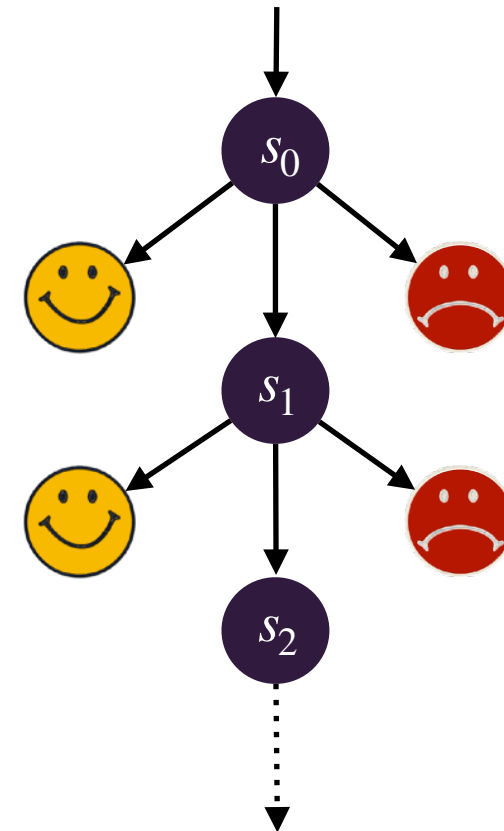
Termination of the approx. scheme

Approximation scheme

Given $\varepsilon > 0$:

$$\begin{cases} p_n^{\text{yes}} &= \mathbb{P}(\mathbf{F}_{\leq n} \text{ 😊 }) \\ p_n^{\text{no}} &= \mathbb{P}(\neg \text{ 😊 } \mathbf{U}_{\leq n} \text{ 😞 }) \end{cases}$$

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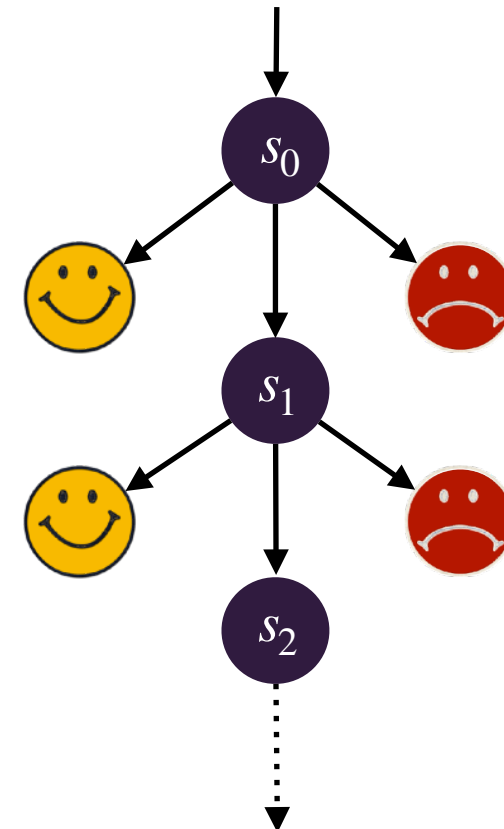
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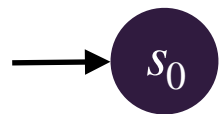
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$\mathcal{C}$ is decisive from s_0 w.r.t. 😊
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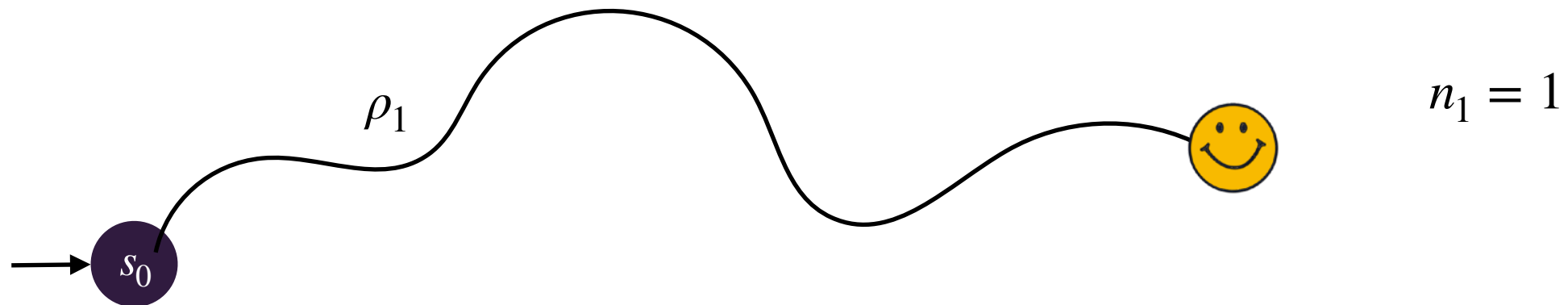
Statistical model-checking

Sample N paths



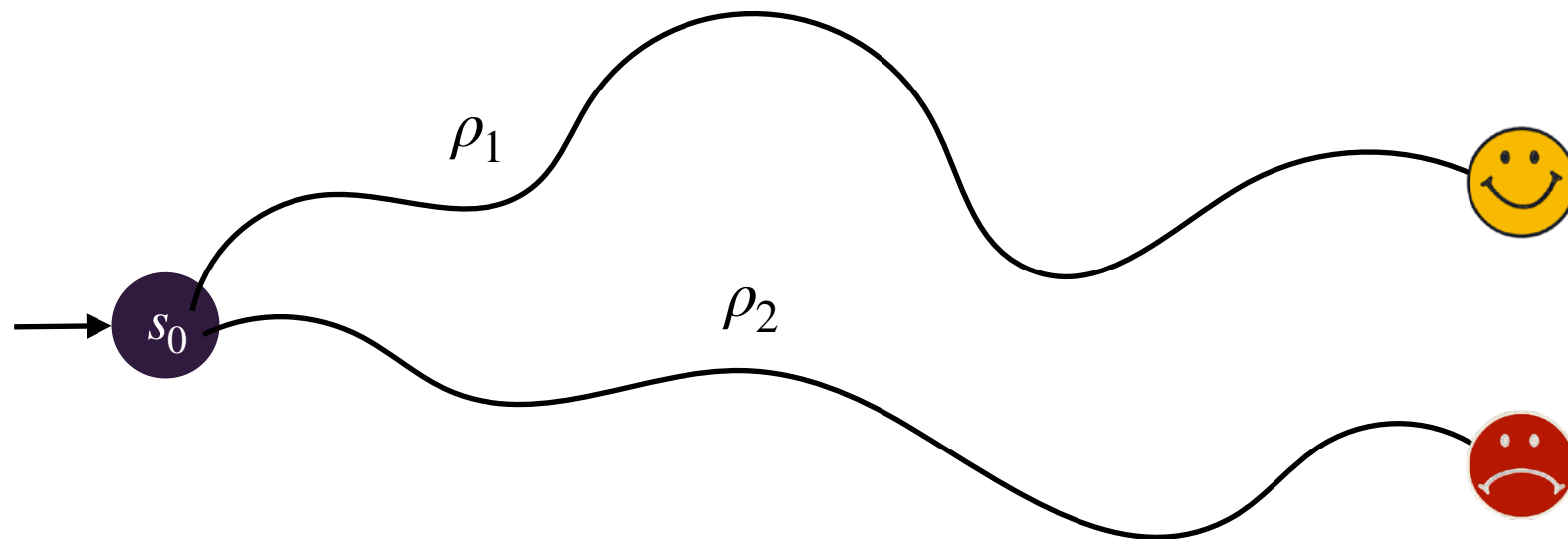
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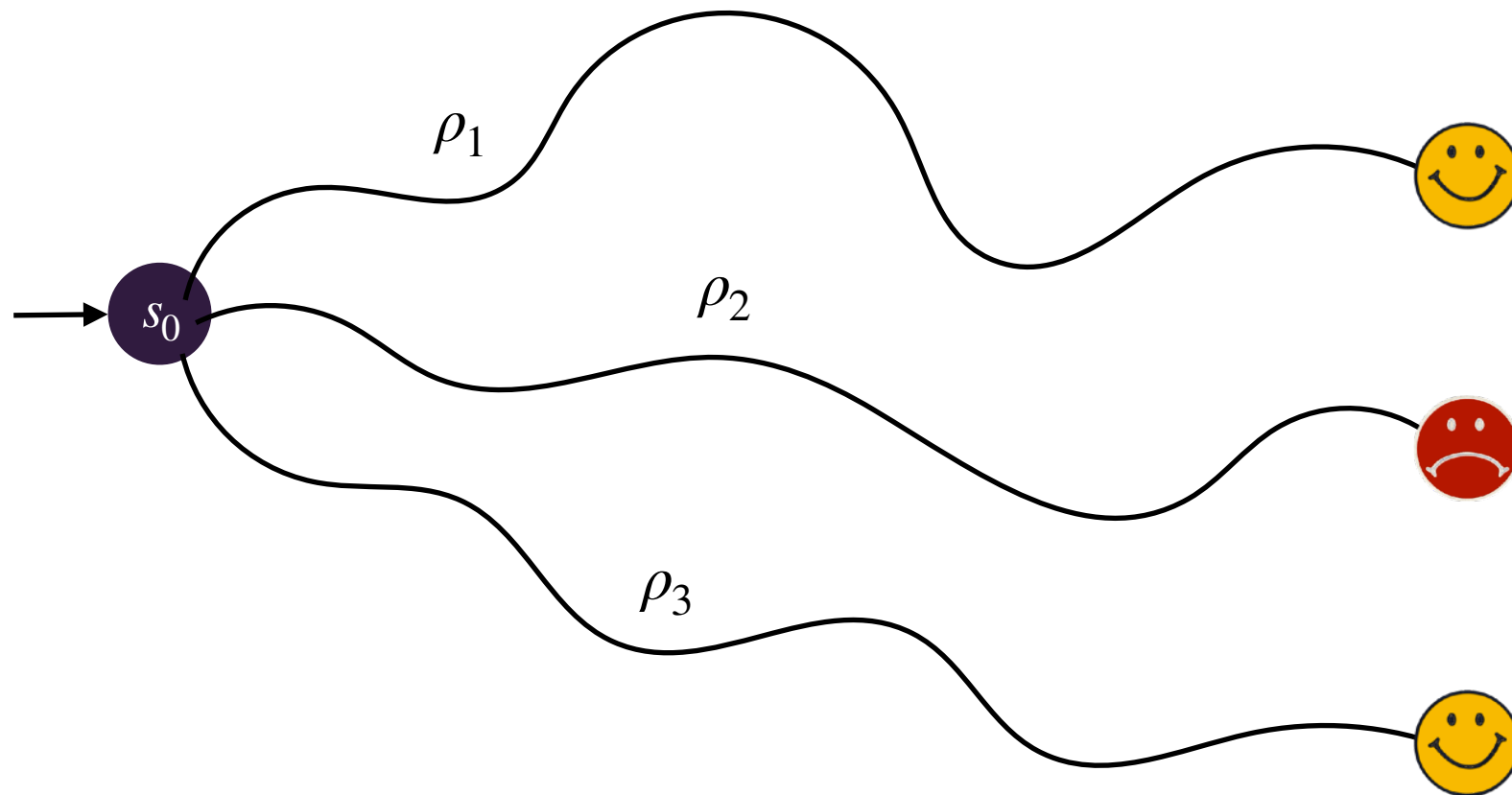


$$n_1 = 1$$

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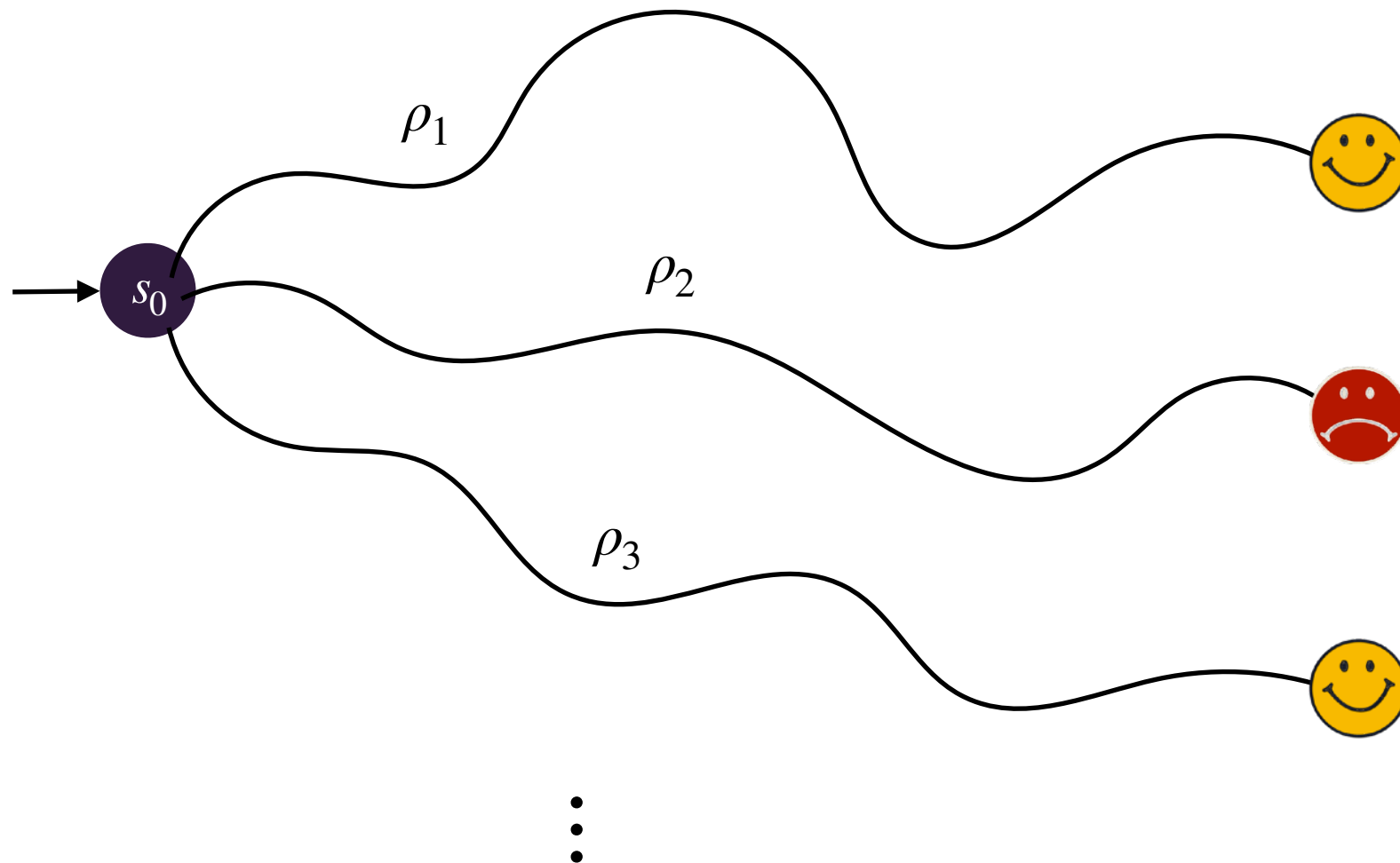
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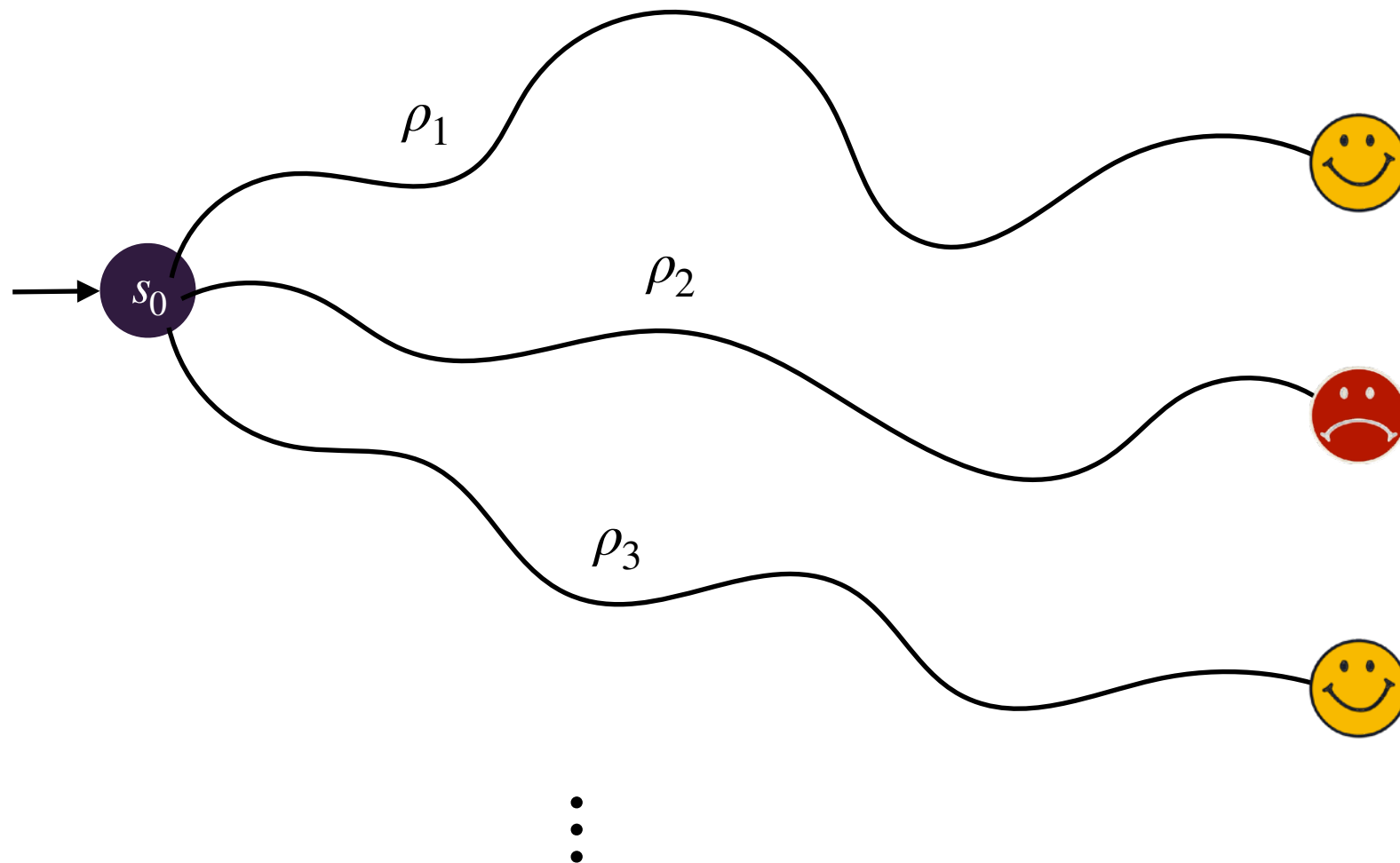
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⋮

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$\vdots$

Return $\frac{n_N}{N} + \text{some confidence interval}$

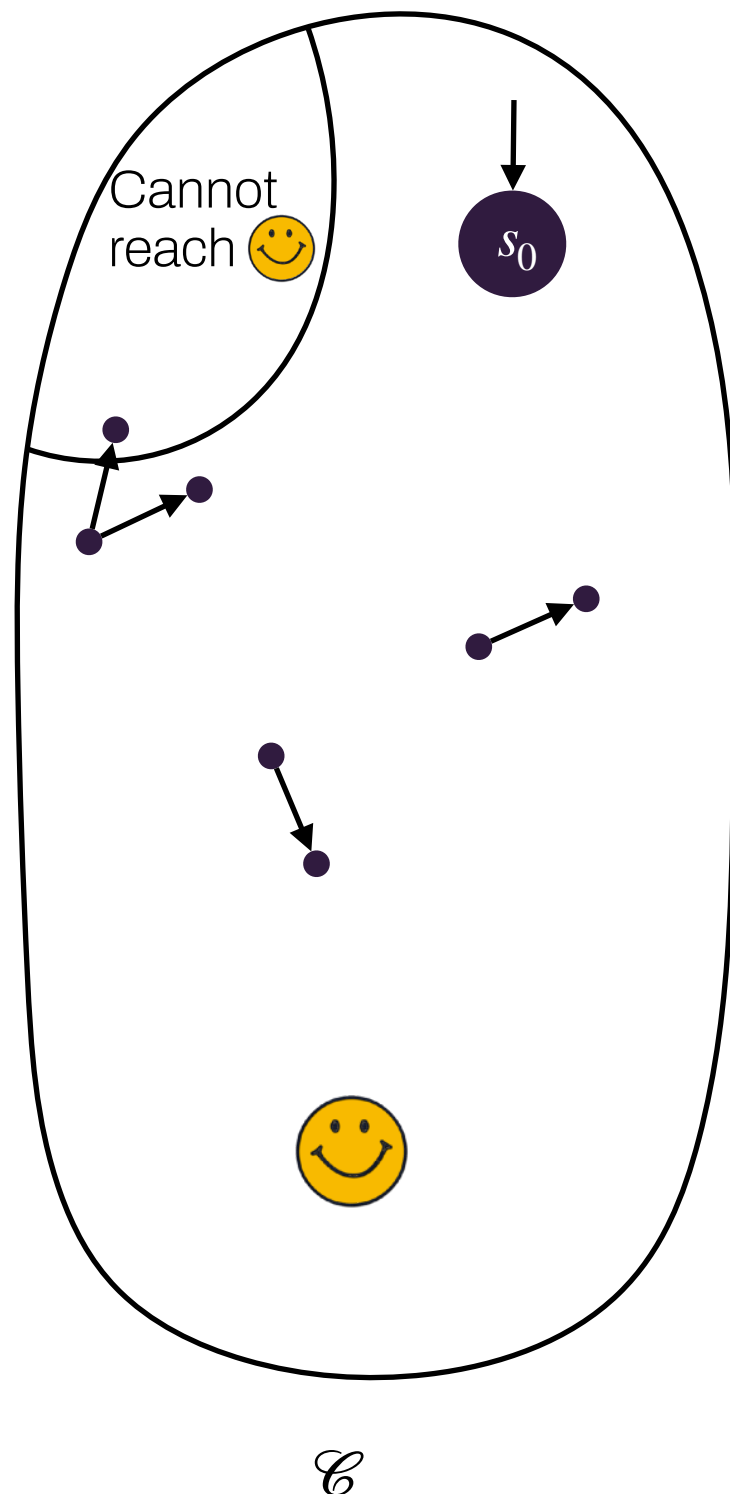
Termination and efficiency

Termination

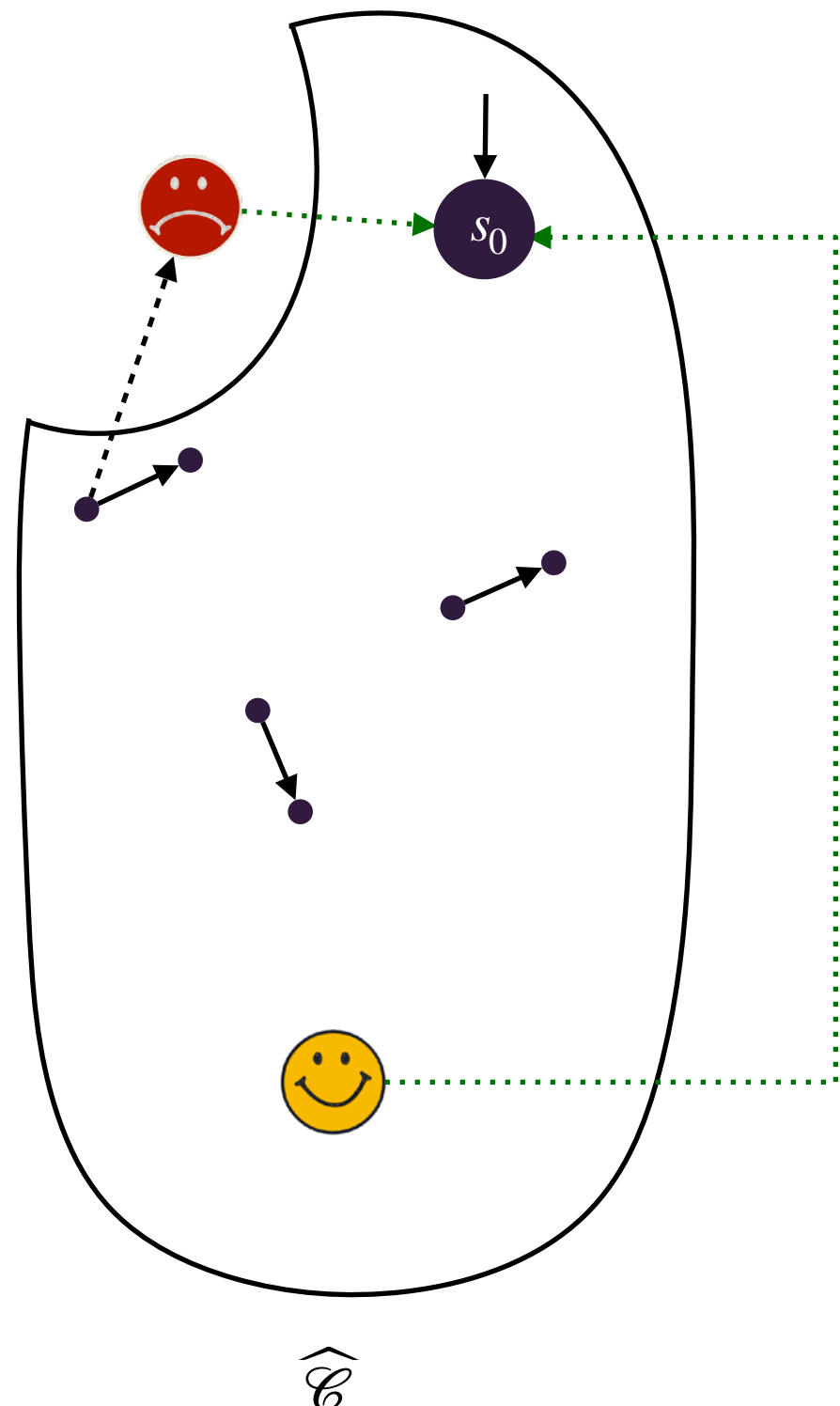
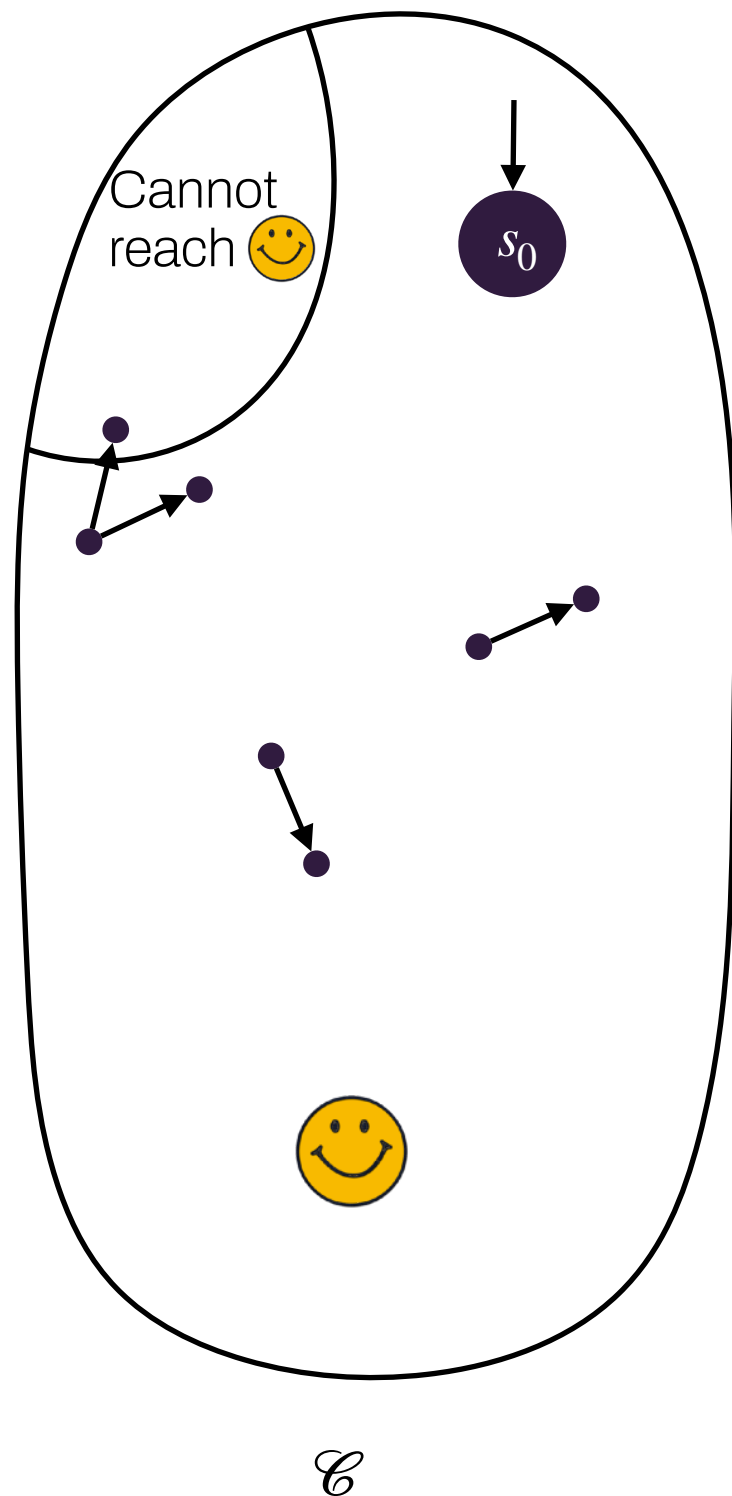
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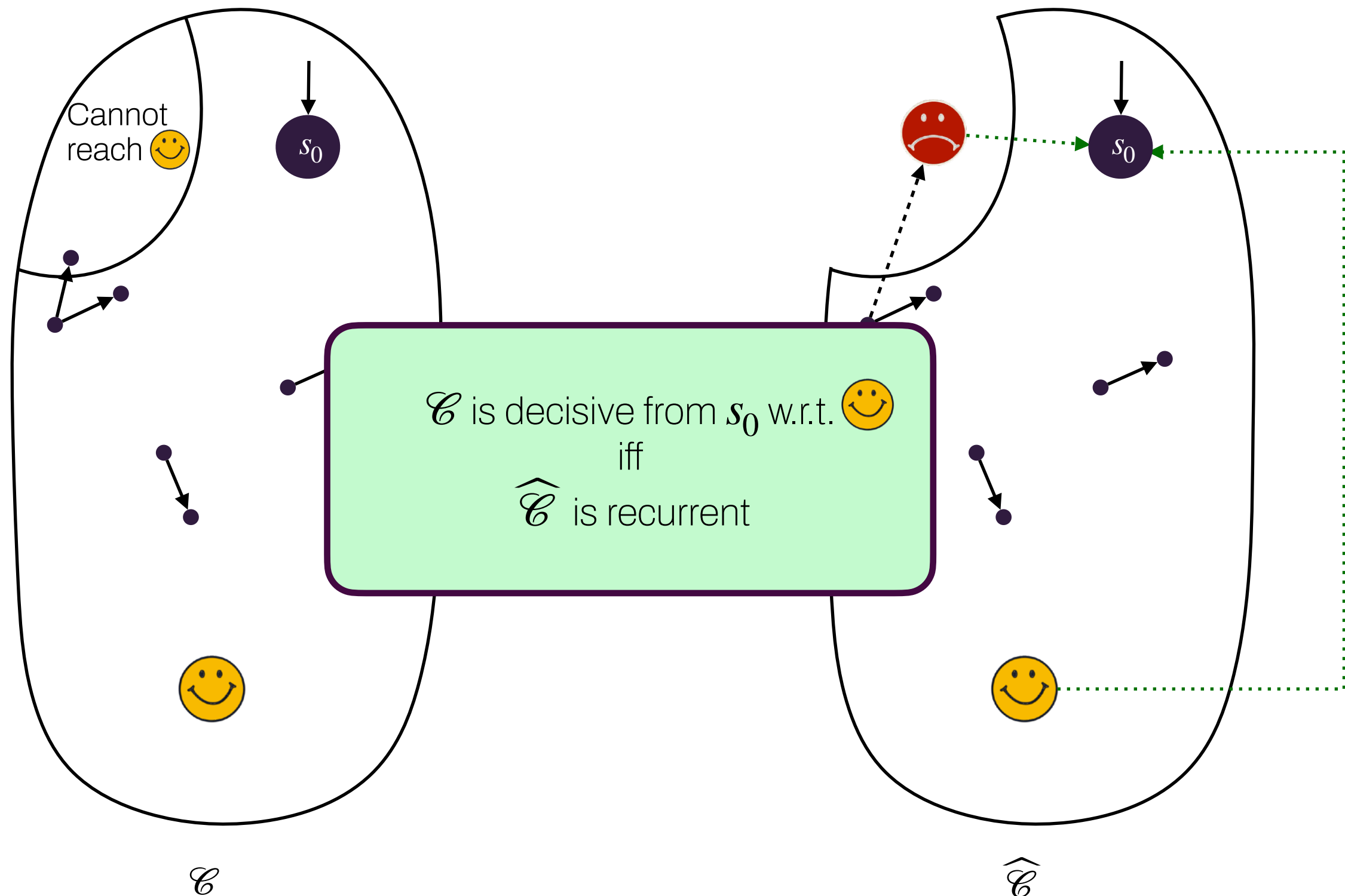
Decisiveness vs recurrence



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The time to sample even increases/diverges!

Statistical guarantees

Hoeffding's inequalities

Let $\varepsilon, \delta > 0$, let $N \geq \frac{8}{\varepsilon^2} \log\left(\frac{2}{\delta}\right)$. Then:

$$\mathbb{P}\left(\left|\frac{n_N}{N} - \mathbb{P}(\mathbf{F} \text{ 😊})\right| \geq \frac{\varepsilon}{2}\right) \leq \delta$$

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Hoeffding's inequalities

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Fix two
parameters, the third
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A slightly more general setting

- ▶ Given $L : S^+ \rightarrow \mathbb{R}$, the 😊-function $f_{L, \text{😊}}$ is $\mathbf{1}_{F \text{😊}} \cdot L$
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Empirical estimation

Let $\varepsilon, \delta > 0$ s.t. $N \geq \frac{8B^2}{\varepsilon^2} \log\left(\frac{2}{\delta}\right)$. Then:

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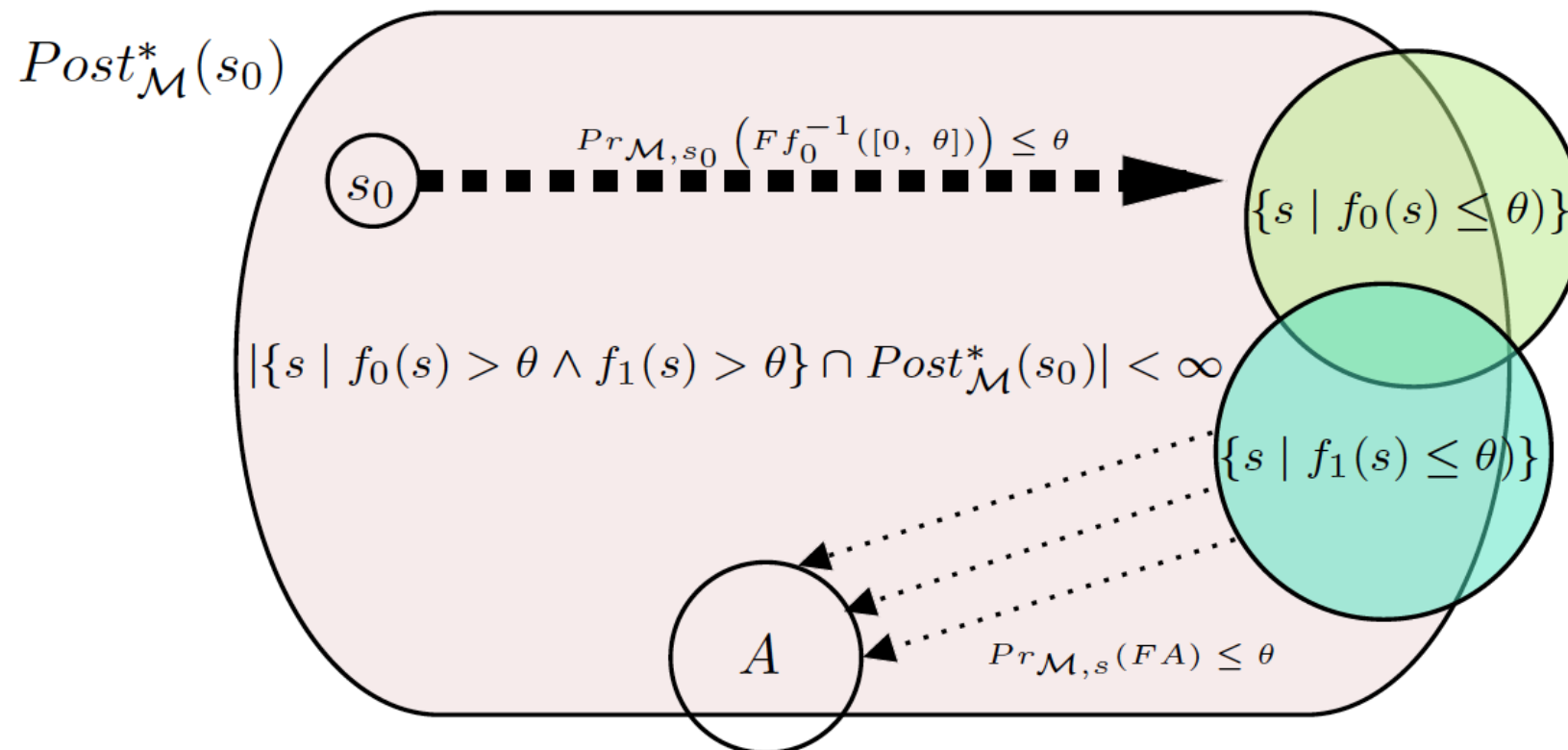
What can we do for
non-decisive Markov chains??

Another numerical generic approach

Divergent Markov Chains

A Markov chain $\mathcal{M}$ is *divergent* w.r.t. s_0 and A if there exist two computable functions f_0 and f_1 from S to $\mathbb{R}_{\geq 0}$ such that:

- ① For all $0 < \theta < 1$, $\mathbf{Pr}_{\mathcal{M}, s_0}(\mathbf{F}f_0^{-1}([0, \theta])) \leq \theta$;
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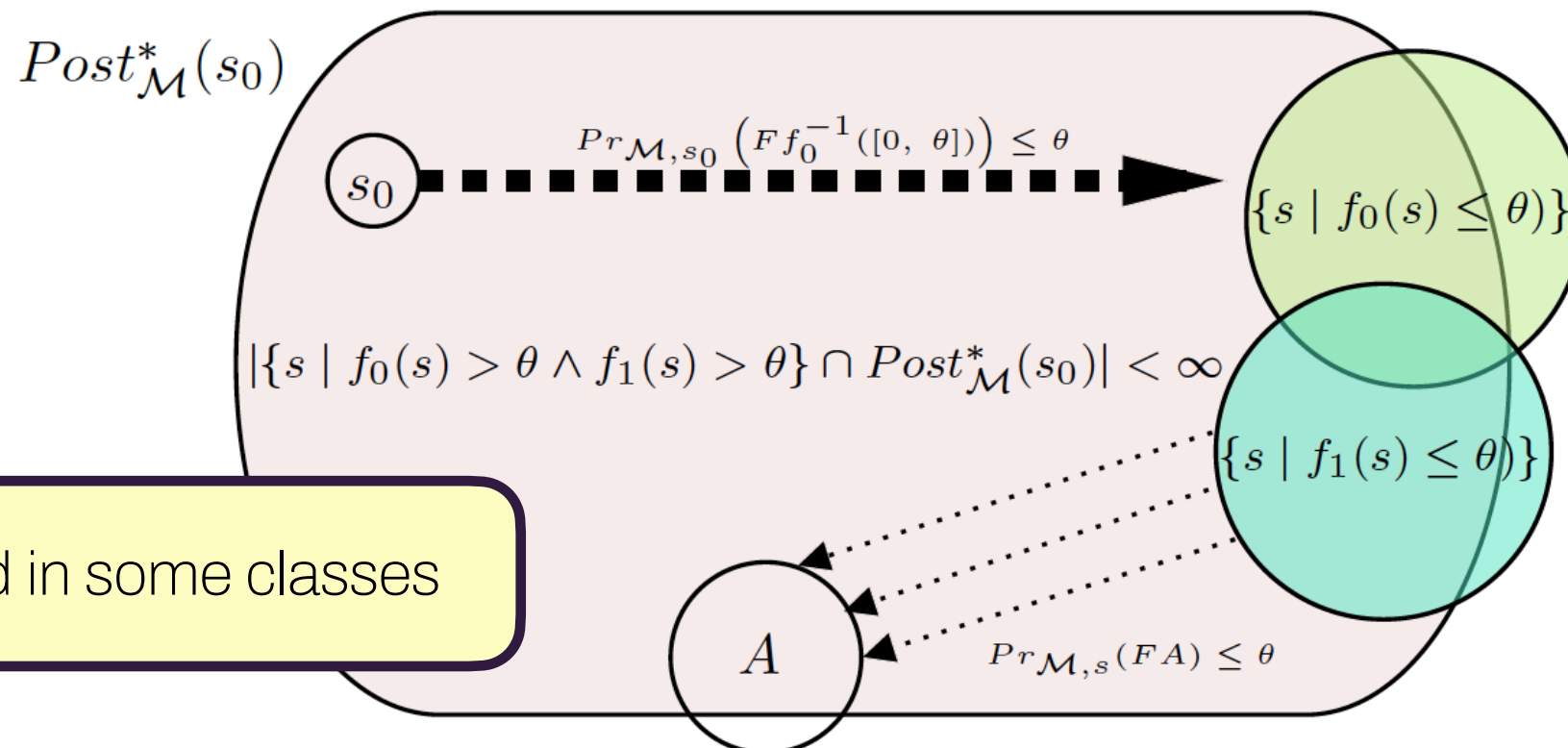


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Can be decided in some classes

Importance sampling for rare events evaluation

- Issue: rare events in $\mathcal{C}$

Rare-Event Problem for Statistical Model Checking

Problem Statement

- We want to estimate the probability of a rare event e occurring with probability close to 10^{-15} .
- We want a *confidence level* of 0.99.
- We are able to compute 10^9 trajectories.

Possible Outcomes

Number of occurrences of e	Probability	Confidence interval
0	$\approx 1 - 10^{-6}$	$[0, 7.03 \cdot 10^{-9}]$
1	$\leq 10^{-6}$	$[6.83 \cdot 10^{-10}, 1.69 \cdot 10^{-9}]$
$n > 1$	$\leq 10^{-12}$	$> 6.83 \cdot 10^{-10}$

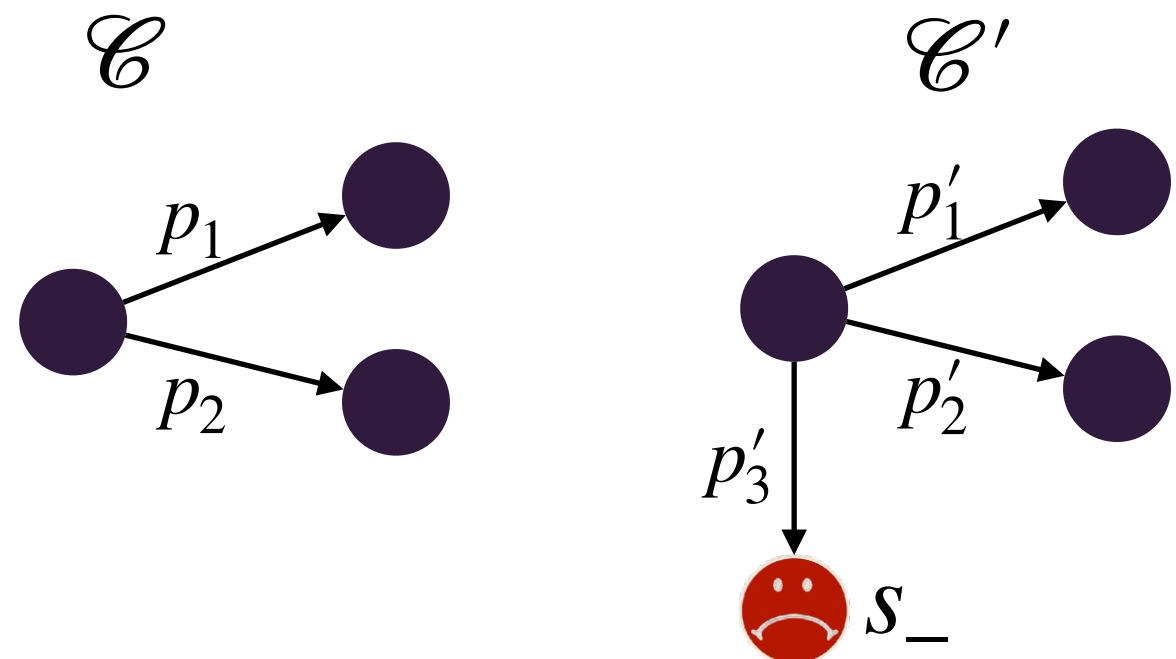
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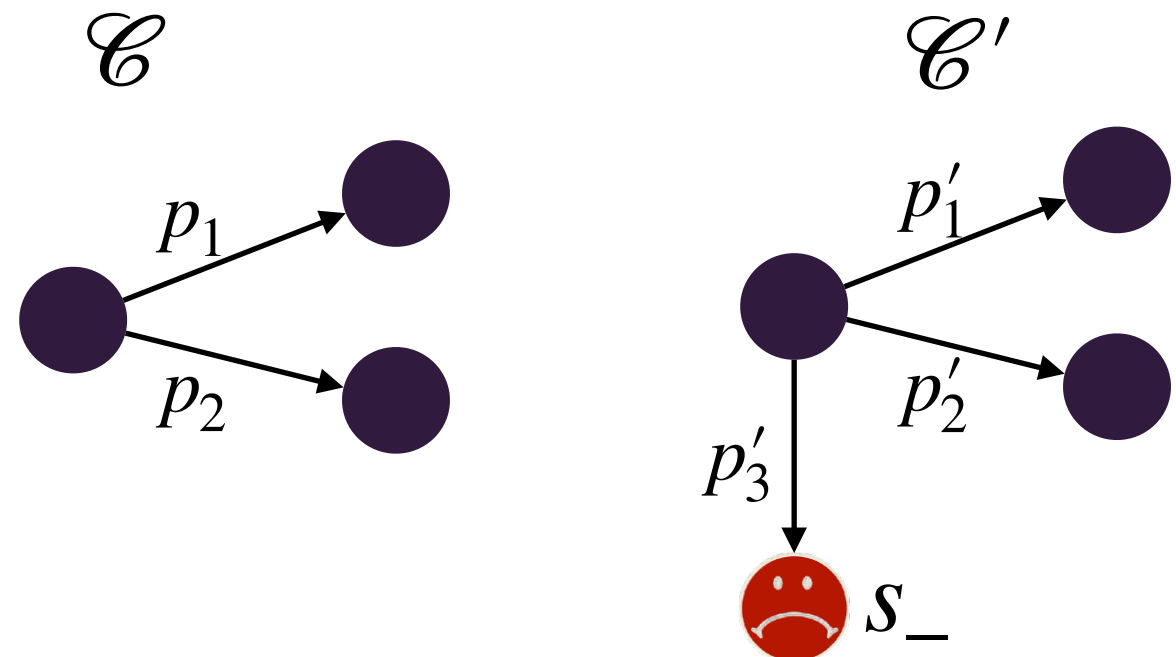
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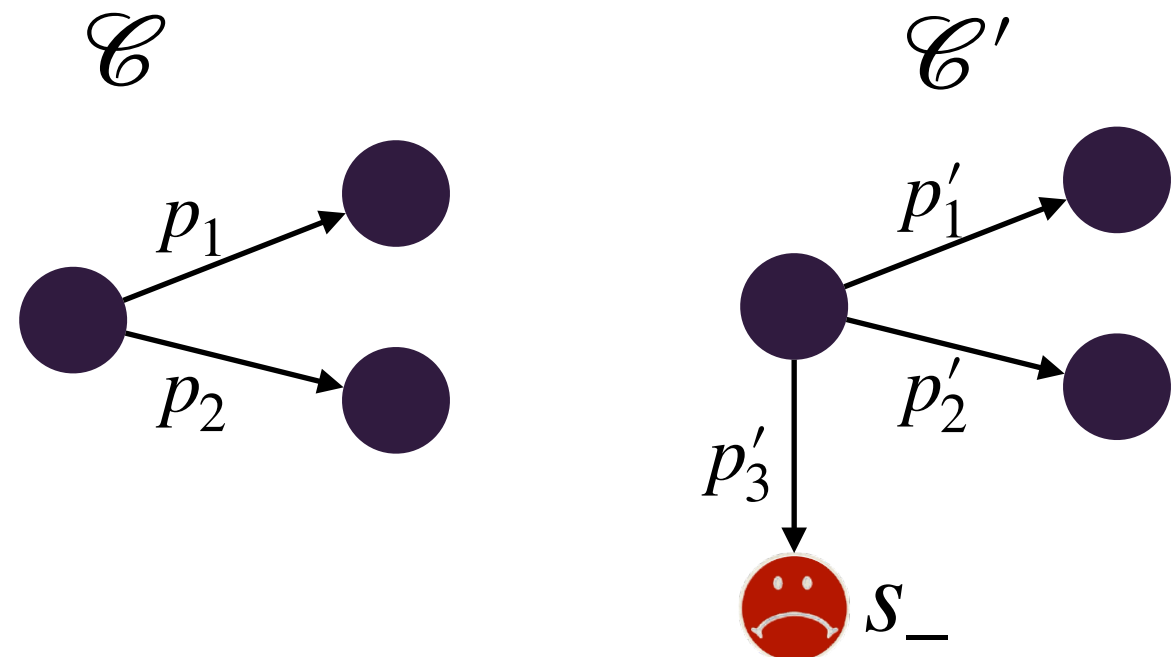
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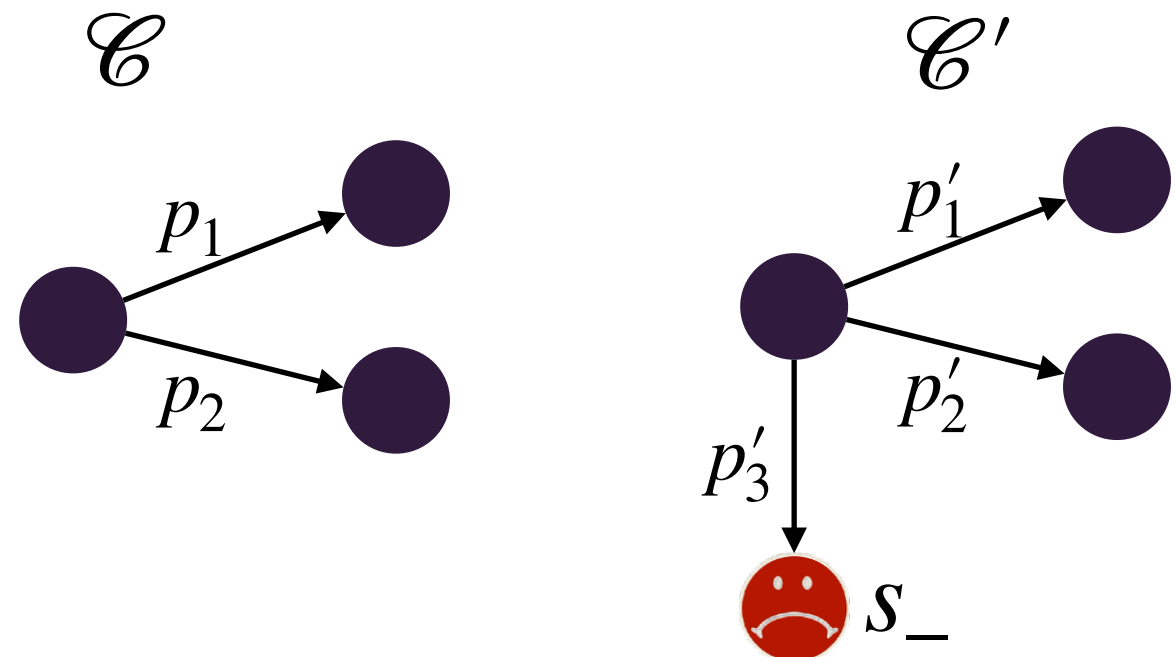
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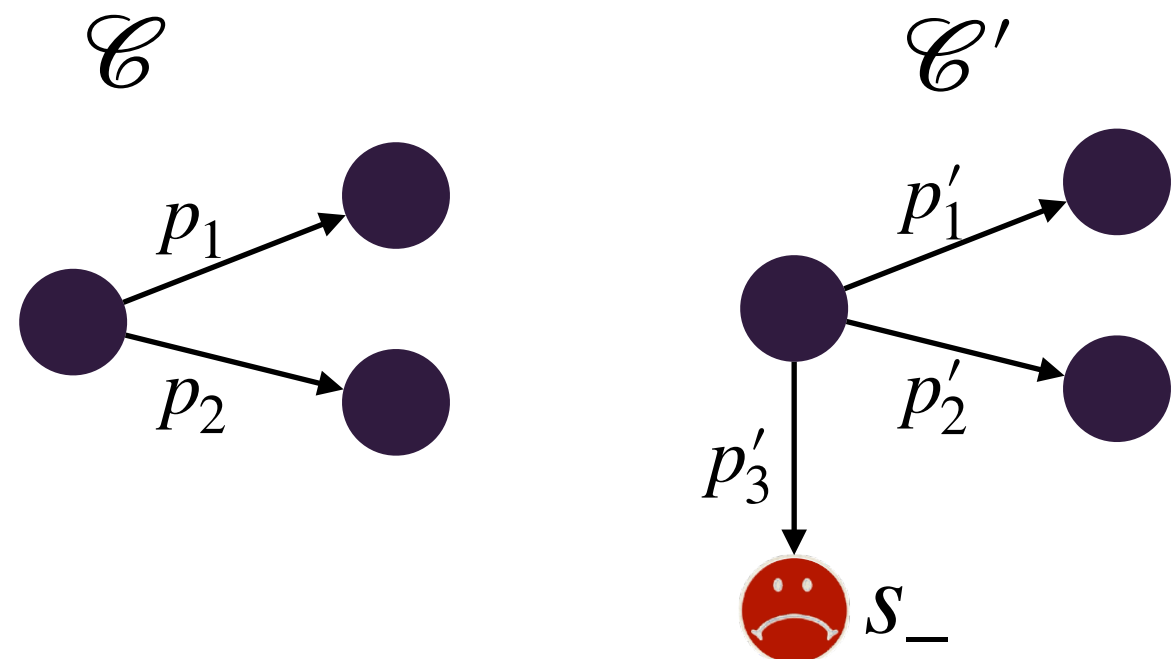
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+ setting giving statistical guarantees

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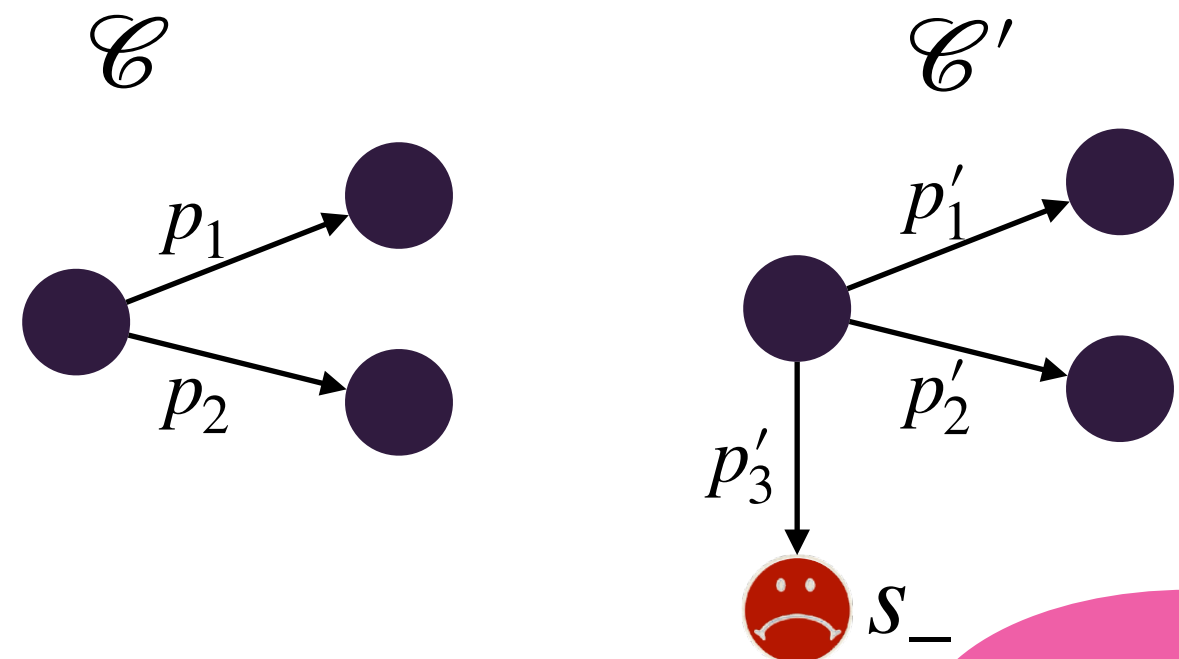
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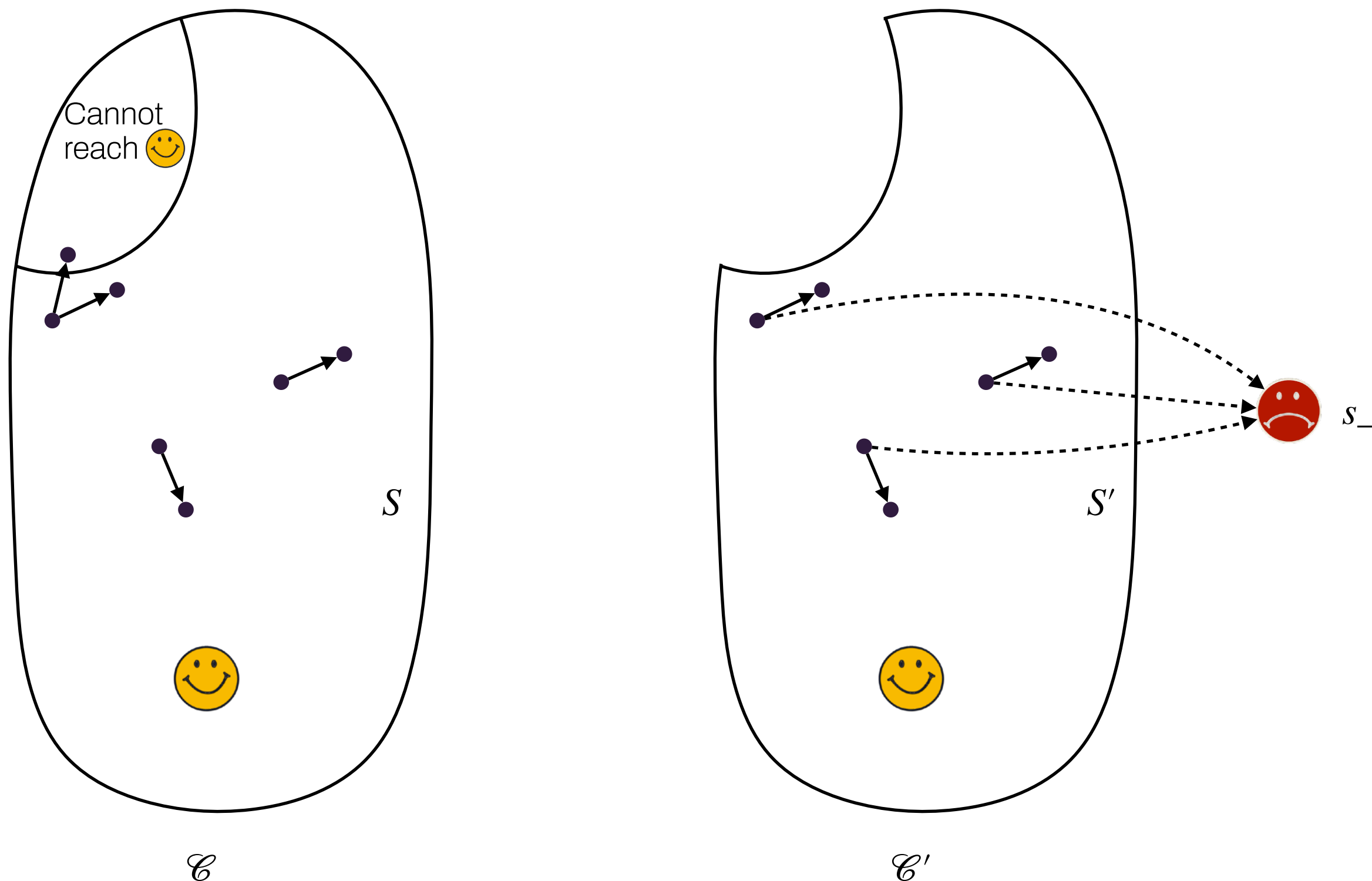
Before that, only estimators!!

We propose to use the importance sampling approach to analyze some non-decisive DTMCs!

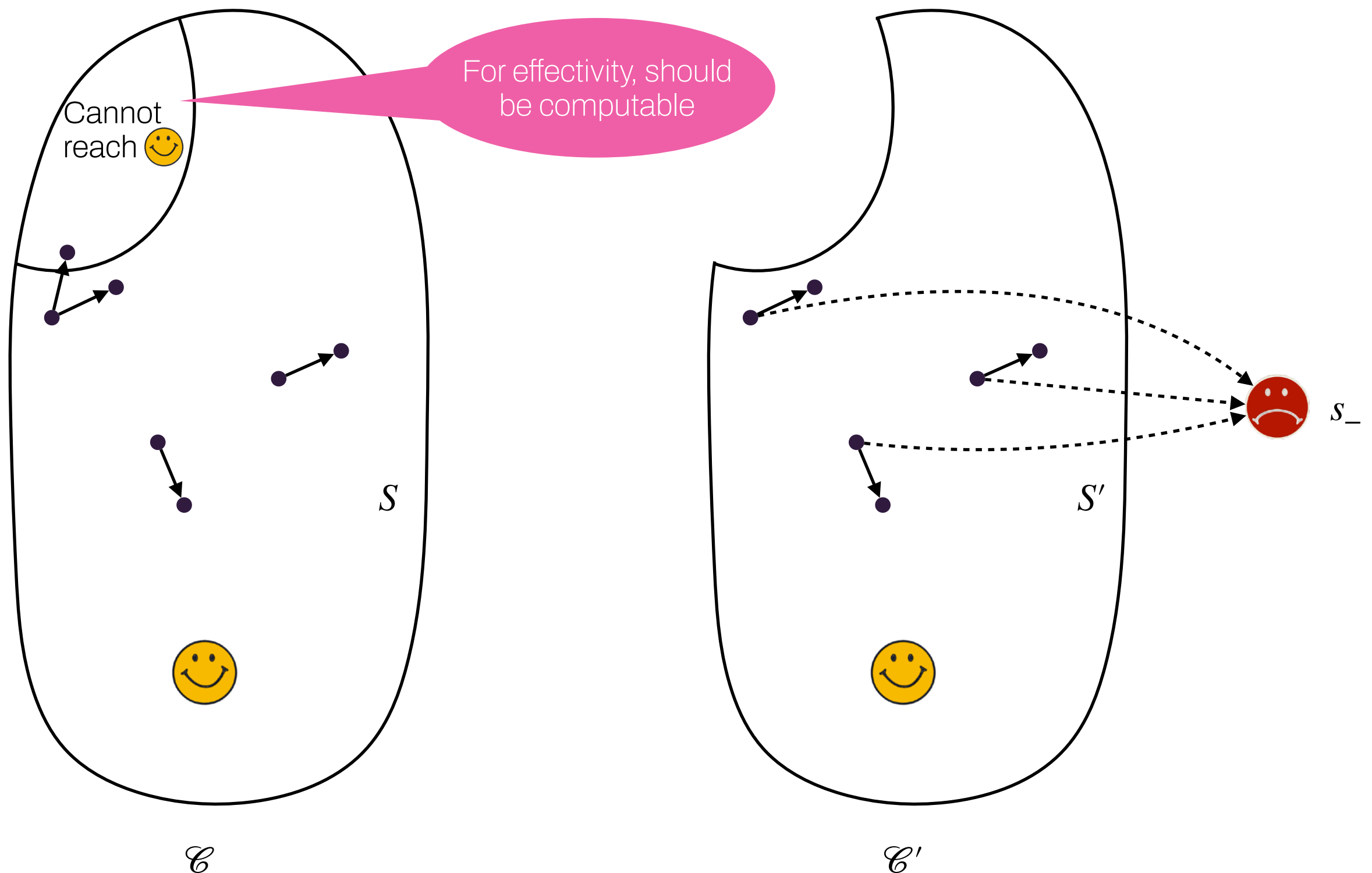
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First time that importance sampling is used not to accelerate the analysis, but to enable the analysis

Biased Markov chain



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Properties of the biased Markov chain

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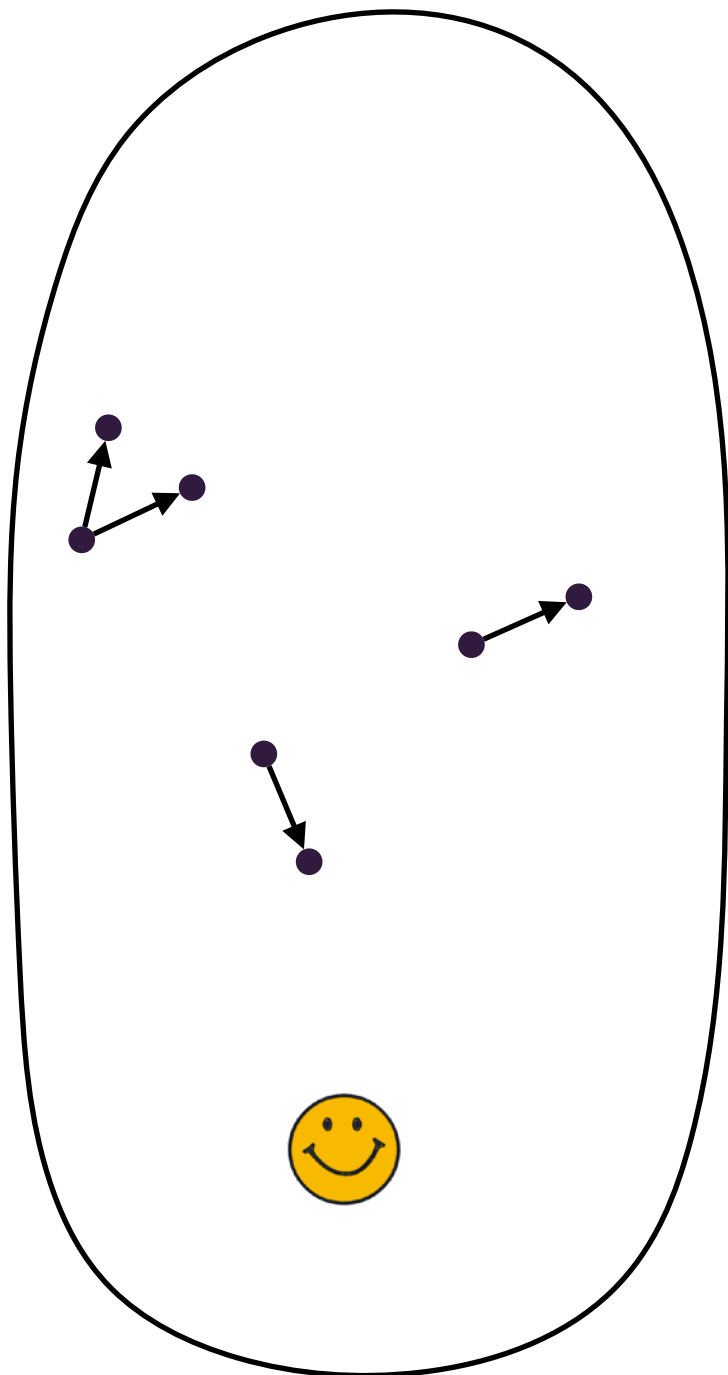
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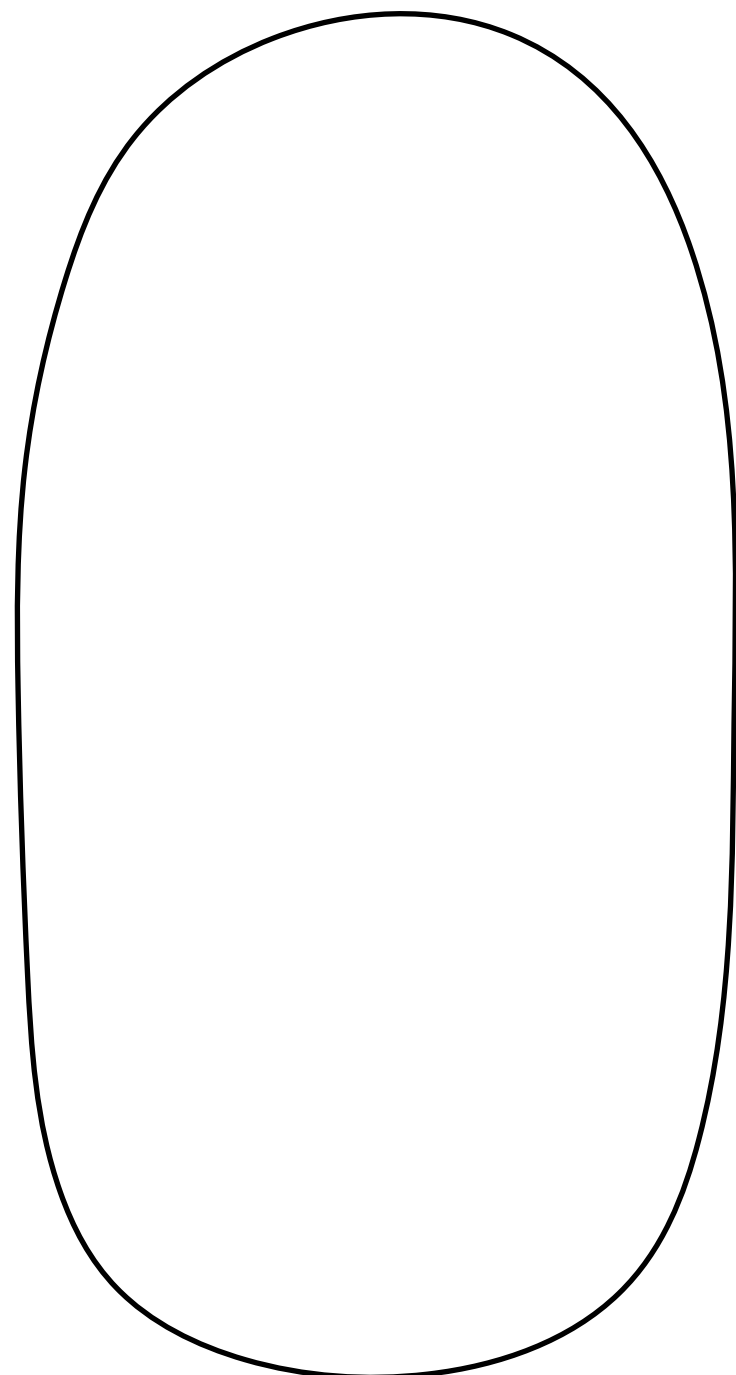
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 - [BHP12] for rare events: approach for finite Markov chains via coupling and abstractions with reduced variance

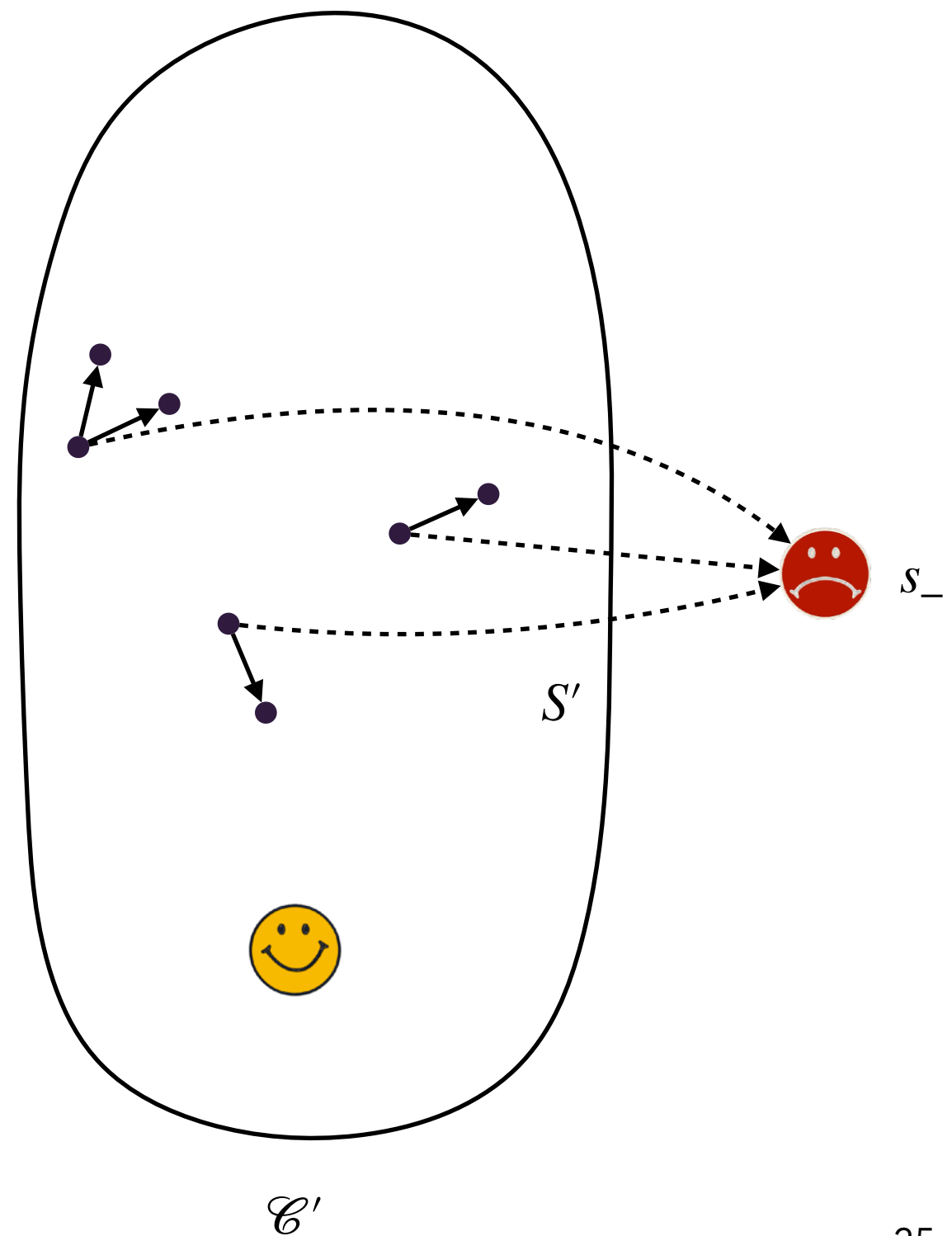
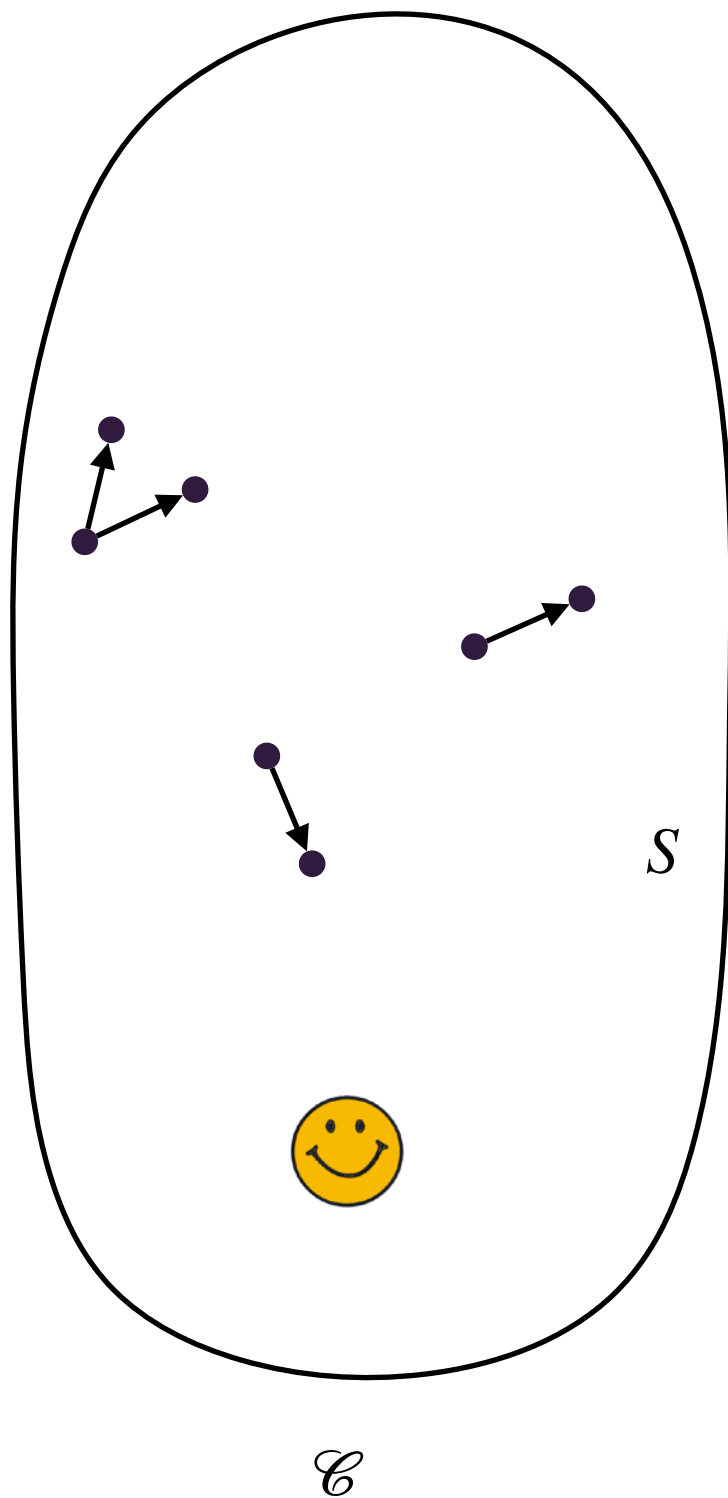
Our approach



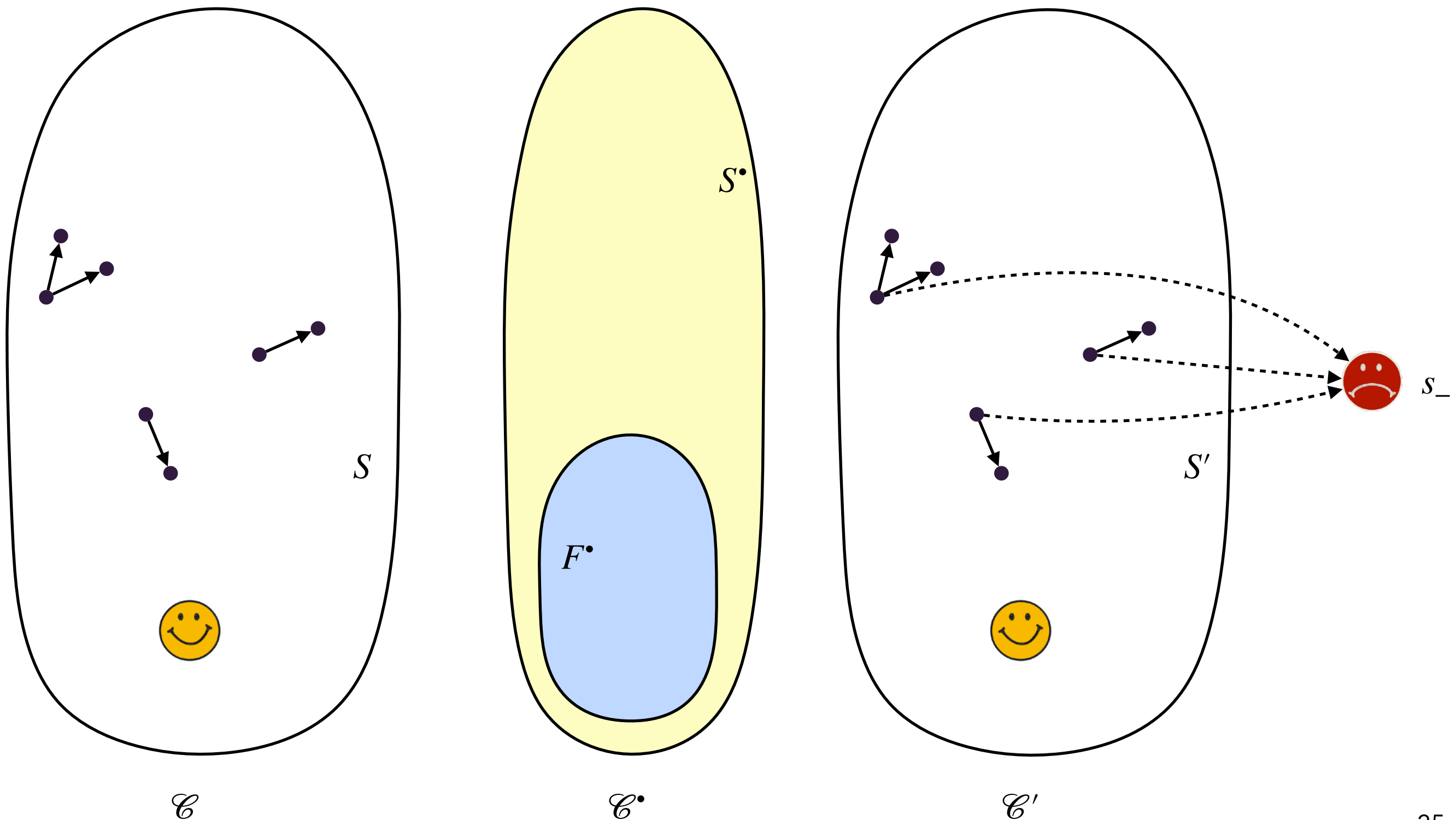
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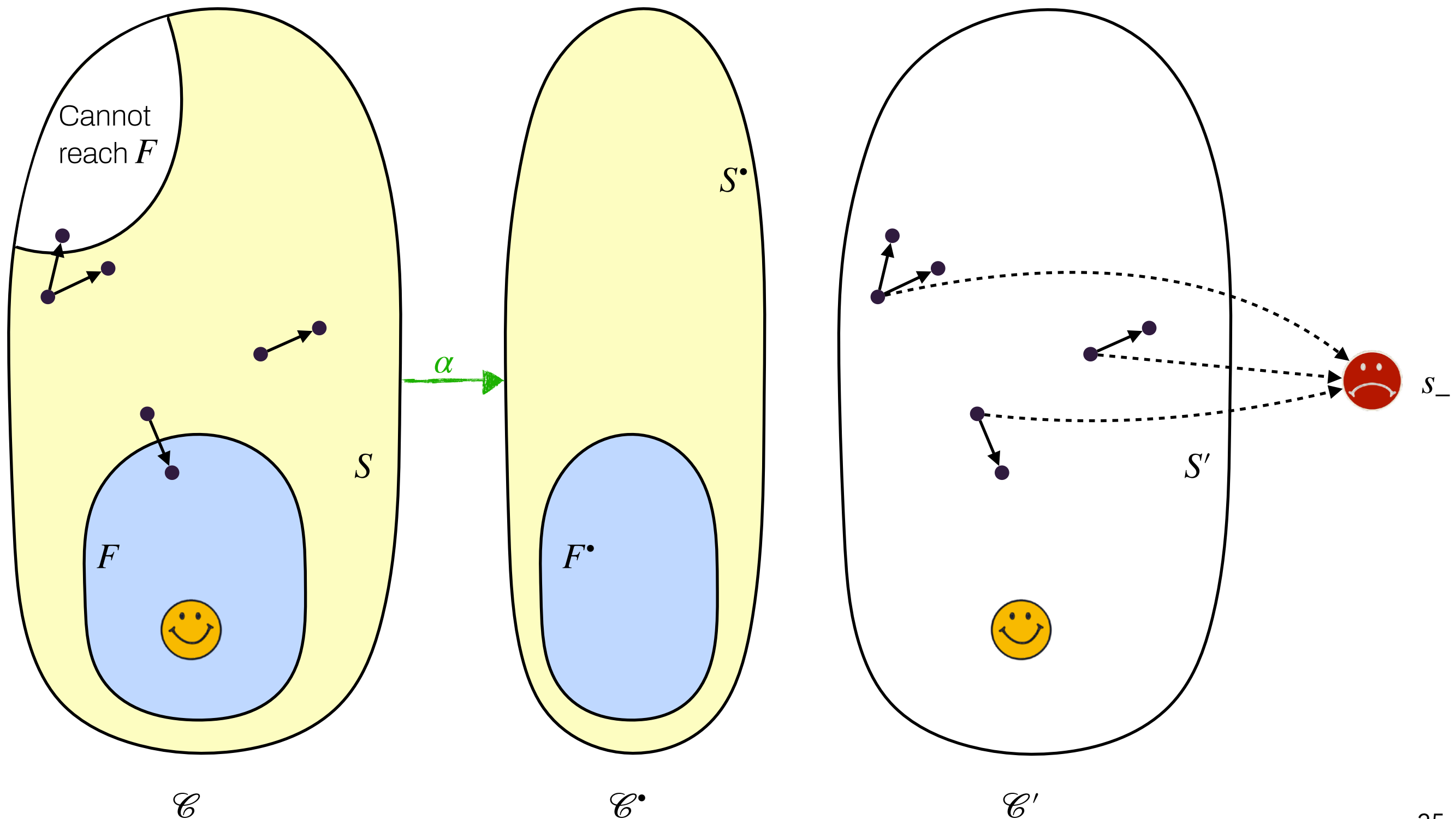
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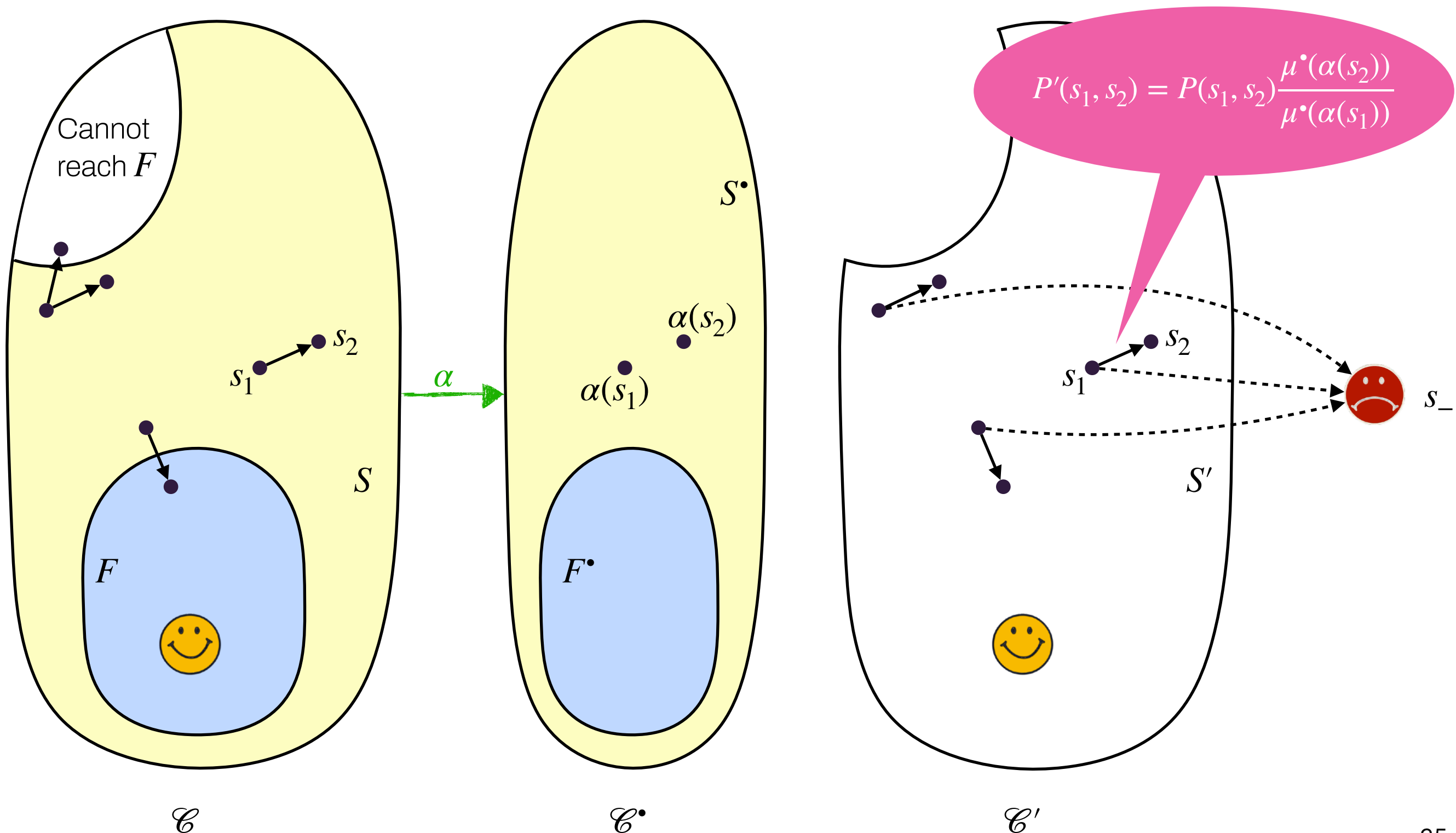
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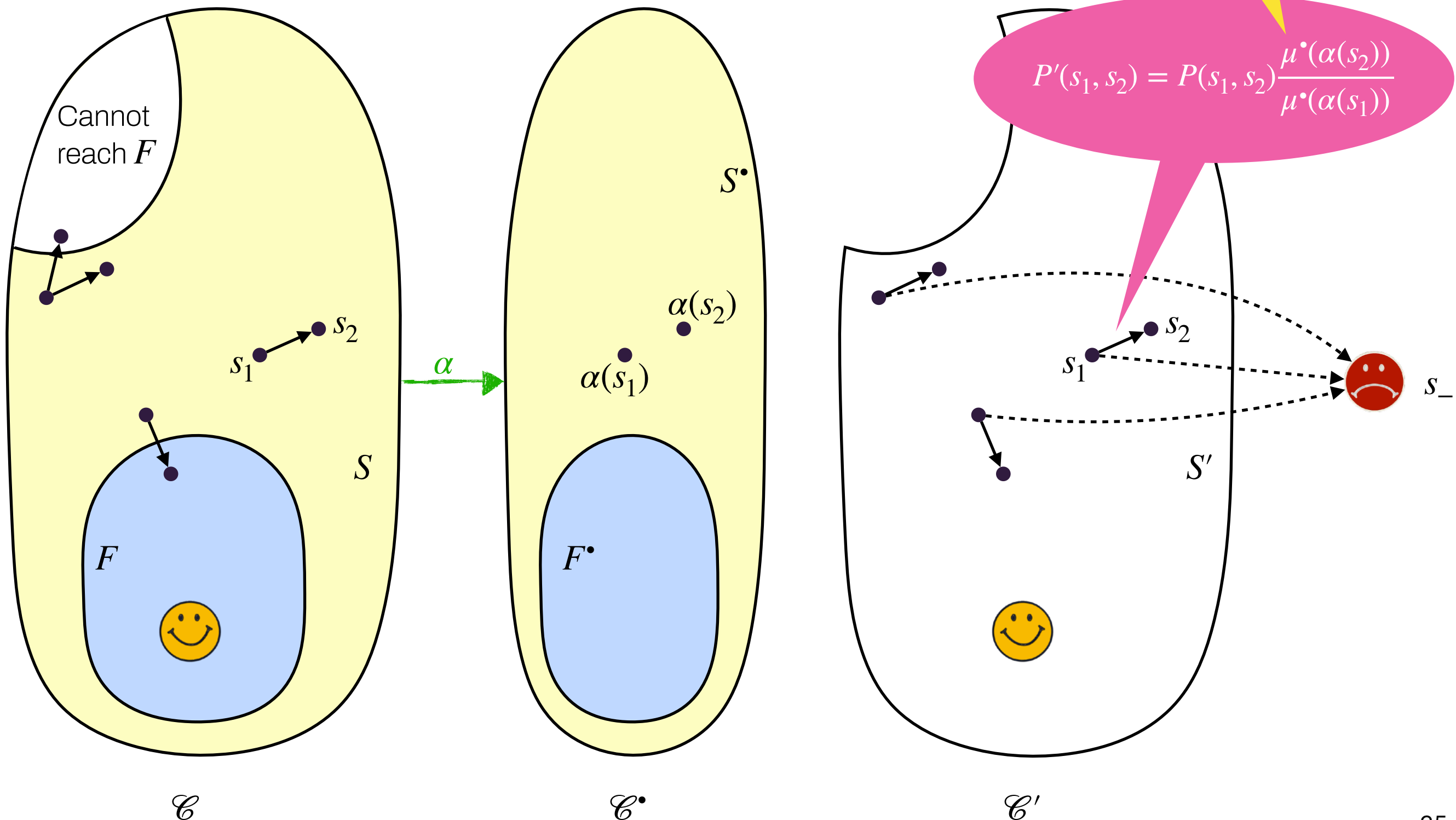


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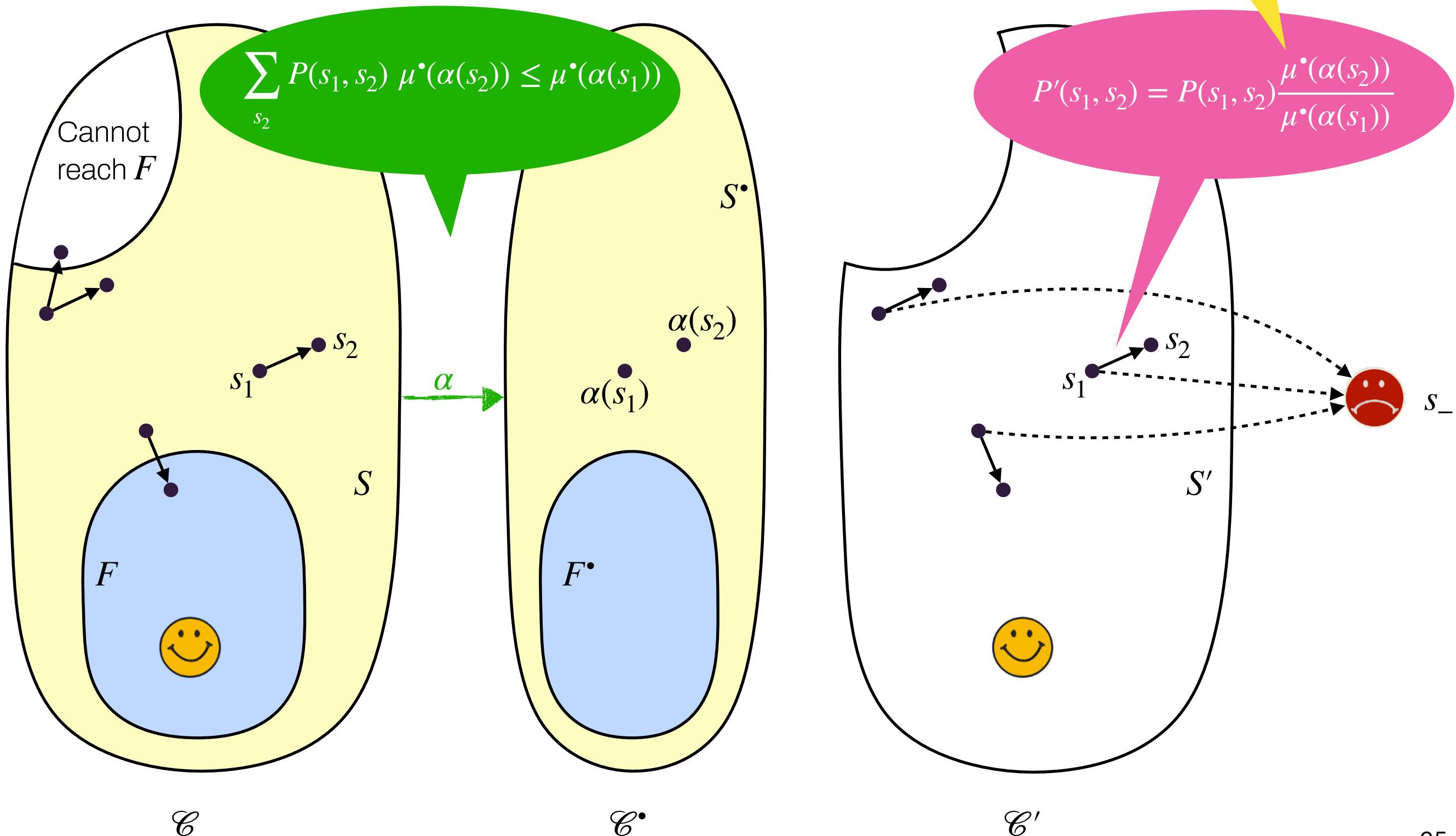
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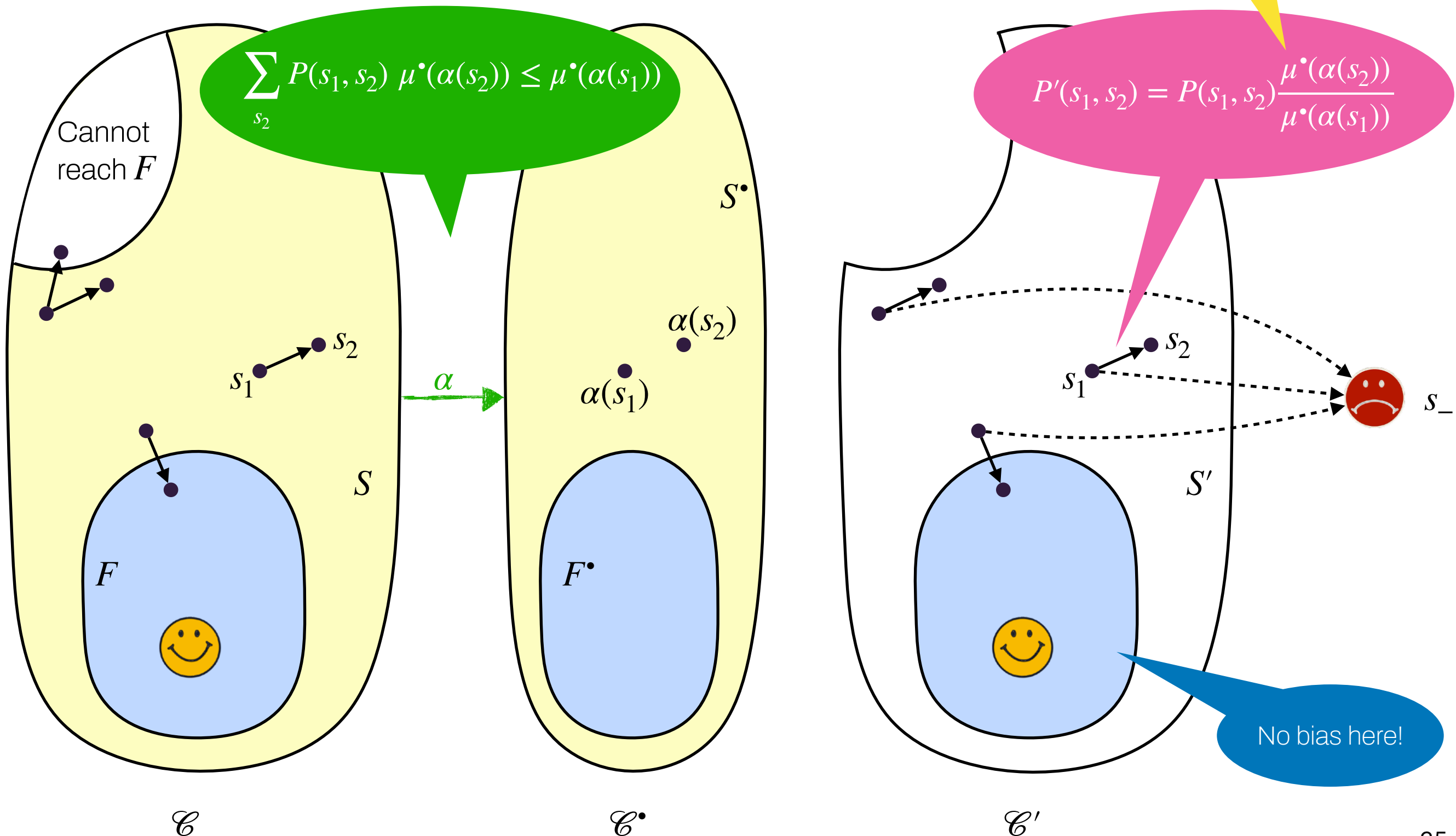
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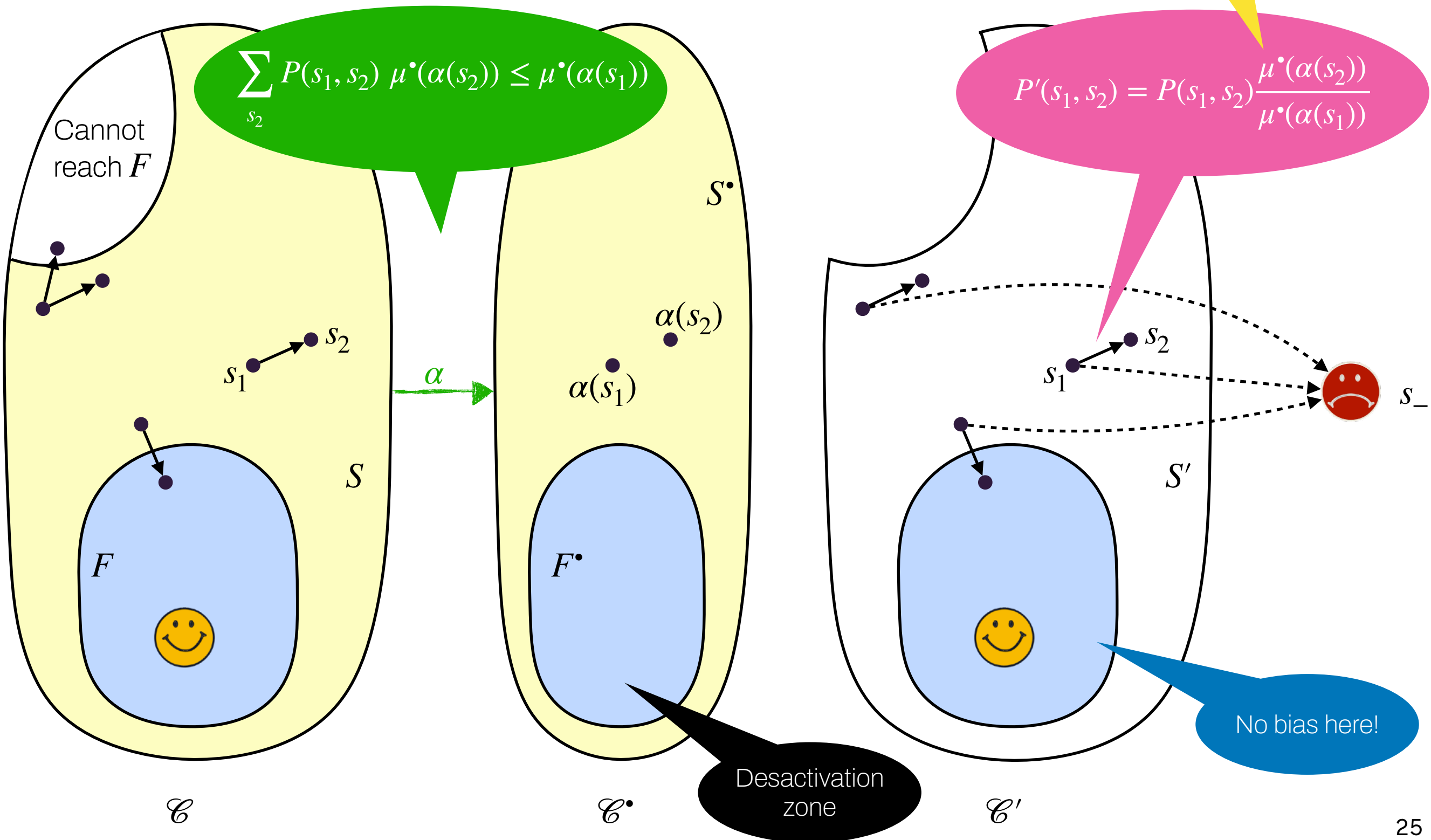
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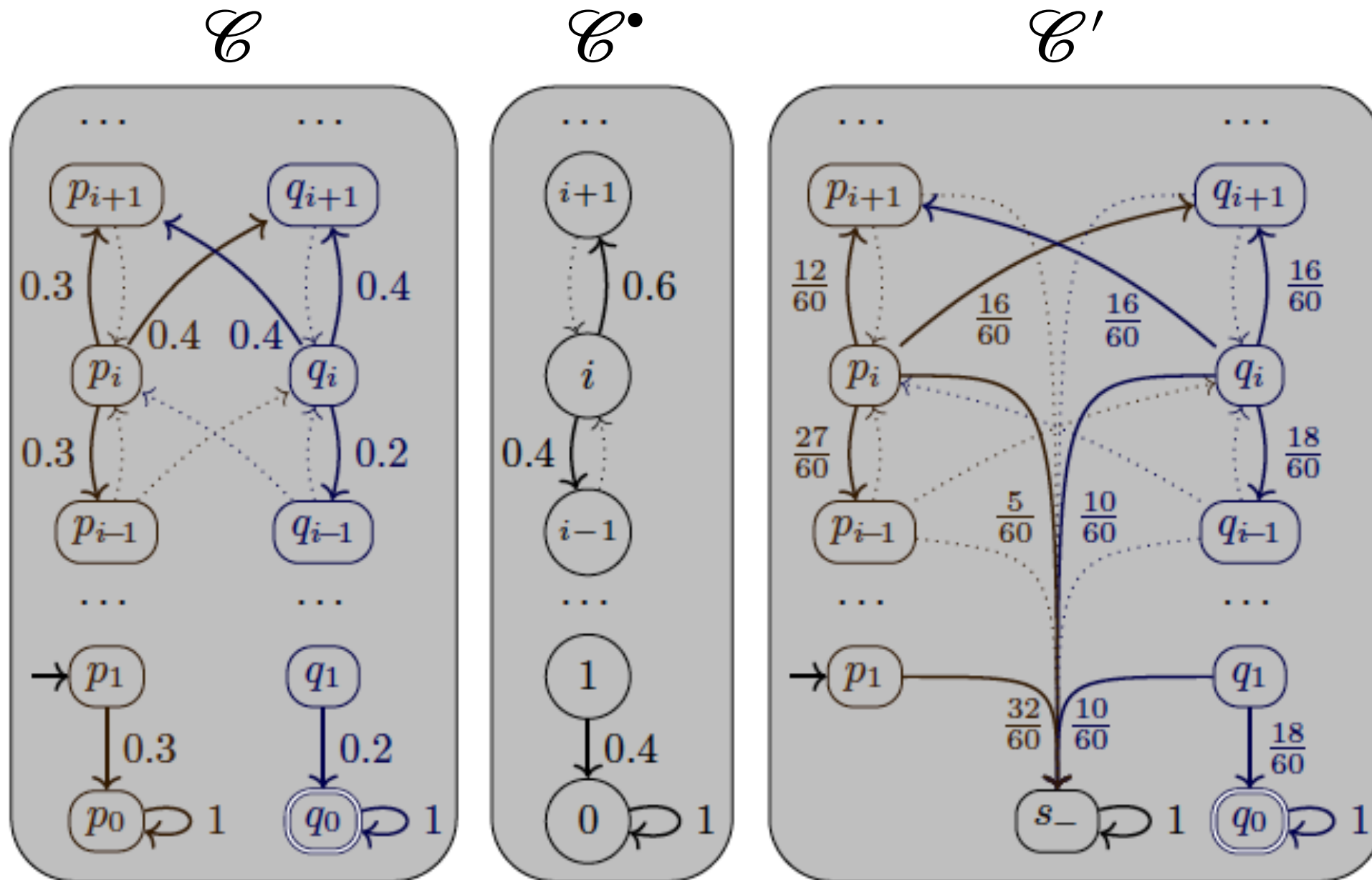
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- ▶ We need:
 - To ensure the decisiveness of $\mathcal{C}'$
 - To compute $\mu^\bullet(\cdot)$ (useful in two places: to sample paths and to compute the final value when hitting 😊)

Role of F

- ▶ Standard approach for importance sampling: no set F (F coincides with 😊)
- ▶ Will be useful to adjust the properties satisfied by the abstraction to be correct
 - Requirement will be « outside F »
 - For instance, congestion of systems

Example



$$F = \{\text{😊}\} = \{q_0\}$$

$\mathcal{C}'$ is decisive

And «concretely»?

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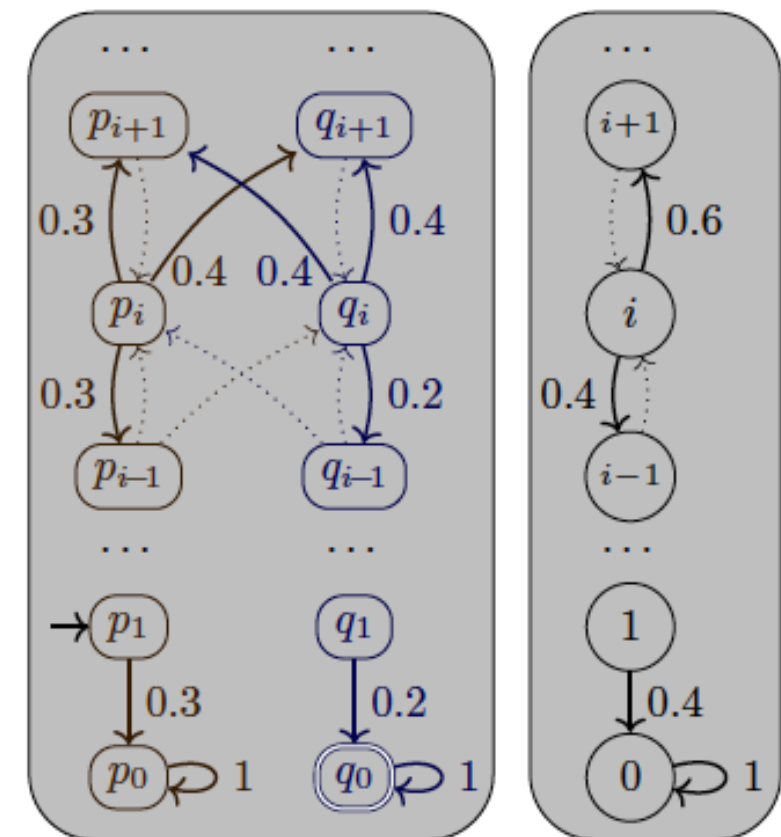
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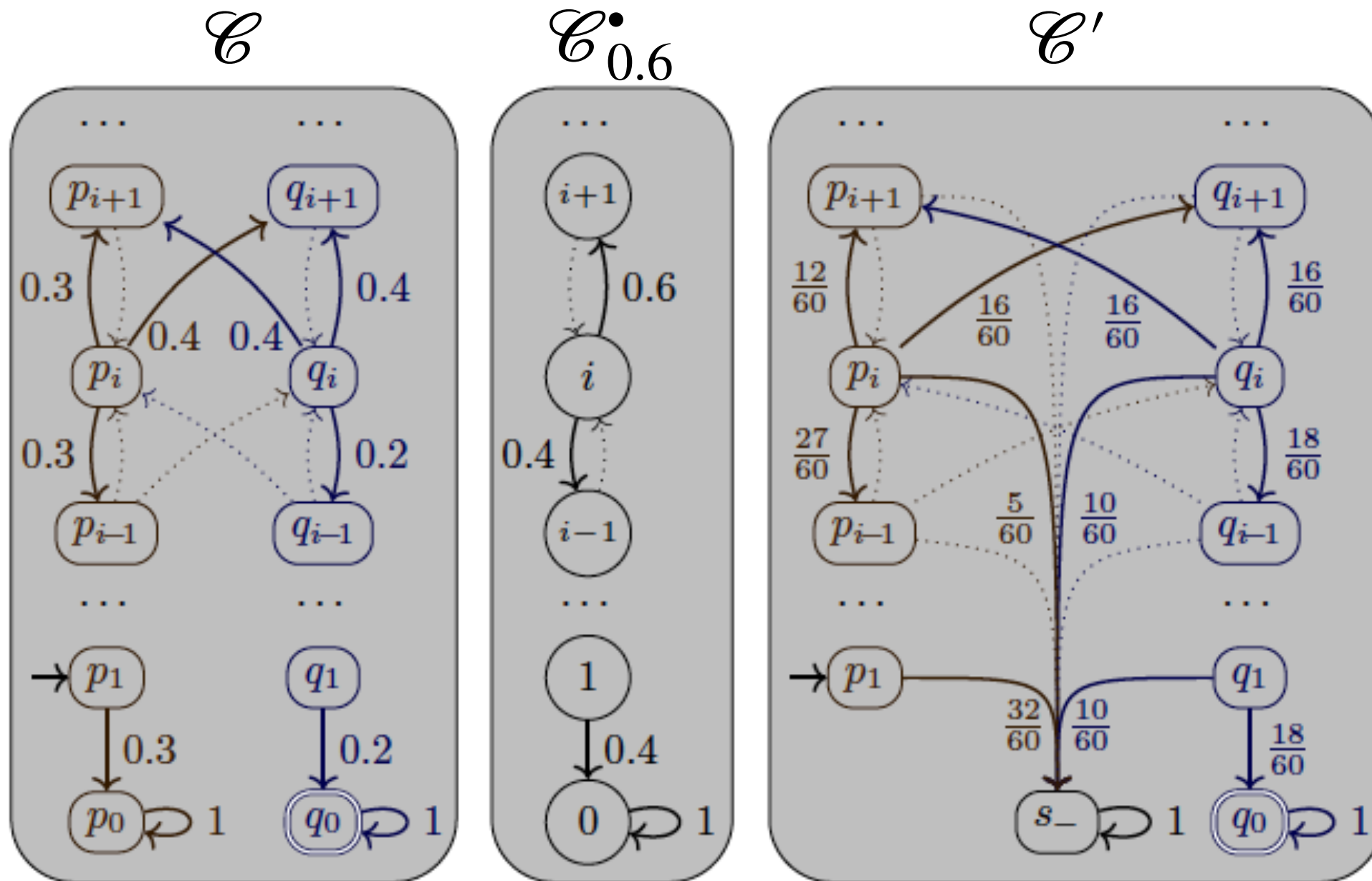
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+ generalization

Example



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$\mathcal{C}'$ is decisive

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- ▶ Local conditions on transition rules to ensure the hypotheses of the theorem

Implementation

<https://cosmos.lacl.fr/>

[BBDHP15] P. Ballarini, B. Barbot, M. Duflot, S. Haddad, N. Pekergin. Hasl: A new approach for performance evaluation and model checking from concepts to experimentation (Performance Evaluation)

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- ▶ Some experiments have been done

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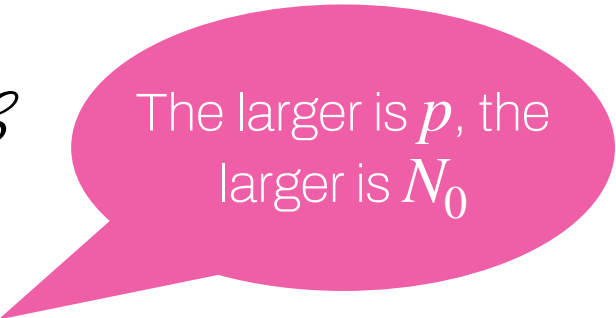
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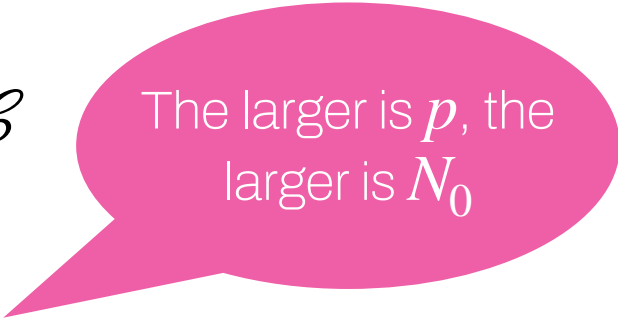
- ▶ If $\mathcal{C}$ is decisive
 - Apply Approx and Estim on $\mathcal{C}$
- ▶ If $\mathcal{C}$ is p -divergent
 - Compute a corresponding N_0



The larger is p , the
larger is N_0

Methodology for experimentations

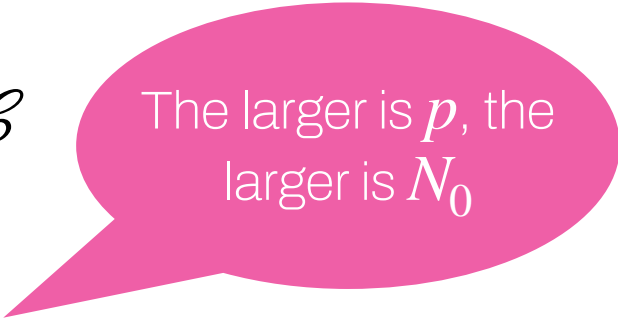
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If $\mathcal{C}$ is p -divergent with N_0 , then $\mathcal{C}$ is p' -divergent with N'_0 as soon as $1/2 < p' \leq p$ and $N'_0 \geq N_0$

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- ▶ p big: large desactivation zone (N_0)
- ▶ p small: small bias (few trajectories end up in s_-)

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What's the trade-off?

Is there a best p ?

- ▶ p big: large desactivation zone (N_0)
- ▶ p small: small bias (few trajectories end up in s_-)

Methodology for experimentations

- ▶ If $\mathcal{C}$ is decisive
 - Apply Approx and Estim on $\mathcal{C}$
- ▶ If $\mathcal{C}$ is p -divergent
 - Compute a corresponding N_0
 - Use the abstraction $\mathcal{C}_p^\bullet$ with desactivation zone $F^\bullet = [0; N_0]$
 - Apply Approx and Estim on $\mathcal{C}'$ (computed on-the-fly)

The larger is p , the larger is N_0

If $\mathcal{C}$ is p -divergent with N_0 , then $\mathcal{C}$ is p' -divergent with N'_0 as soon as $1/2 < p' \leq p$ and $N'_0 \geq N_0$

What's the trade-off?

Is there a best p ?

- ▶ p big: large desactivation zone (N_0)
- ▶ p small: small bias (few trajectories end up in s_-)

Note: in all experiments, the confidence is set to 99 %

First example

- ▶ State-free proba. pushdown automaton $\mathcal{C}$

$$A \xrightarrow{1} C \quad A \xrightarrow{n} BB \quad B \xrightarrow{5} \varepsilon$$

$$B \xrightarrow{n} AA \quad C \xrightarrow{1} C$$

- ▶ Start from A , and target the empty stack

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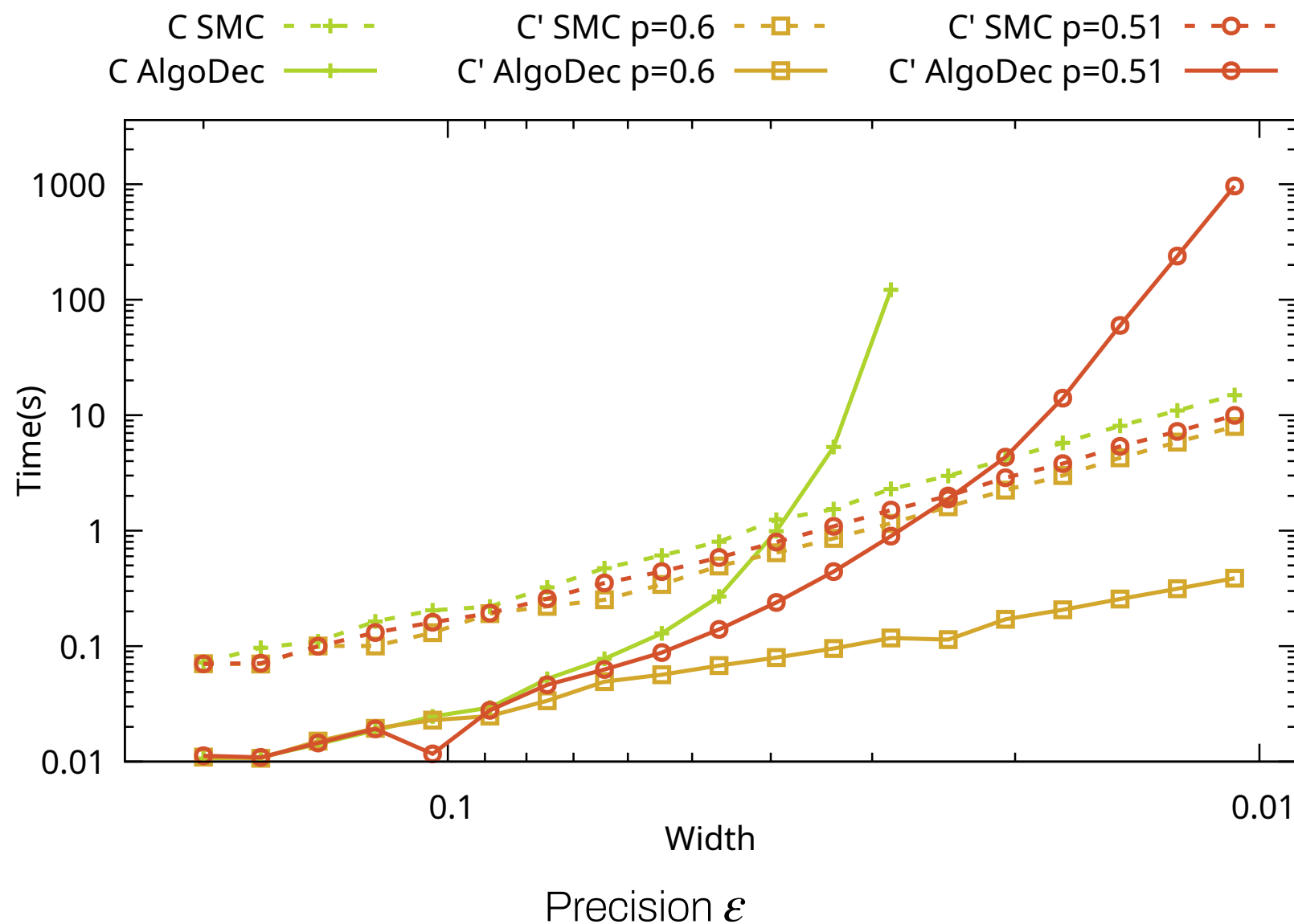
$$B \xrightarrow{n} AA \quad C \xrightarrow{1} C$$

- ▶ Start from A , and target the empty stack

- ▶ It is decisive
- ▶ It is p -divergent for every $1/2 < p < 1$

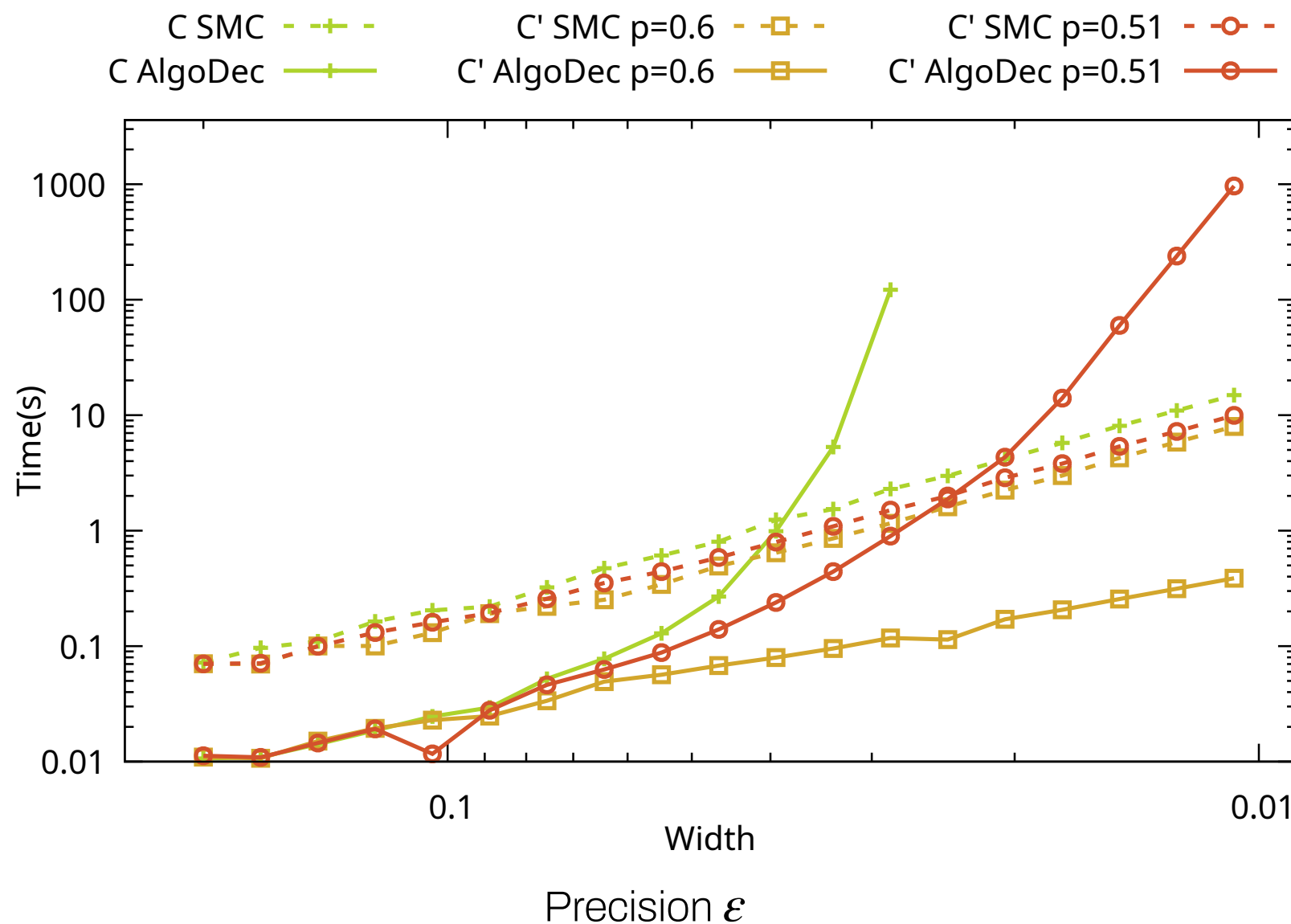
First example

Experimental results



First example

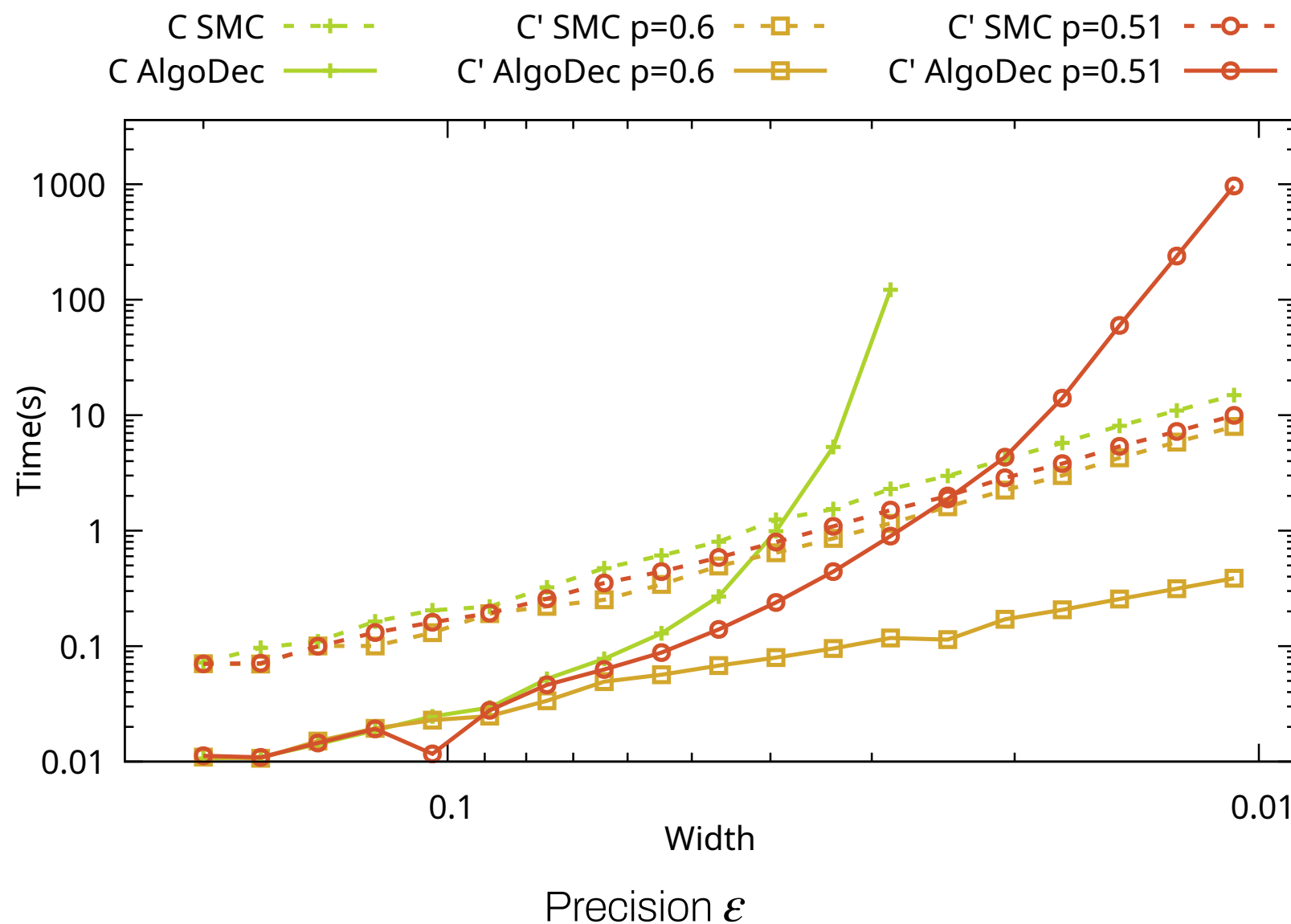
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- In Estim (SMC): doubling the precision impacts in square on computation time (slope 2 in this log-log scale)

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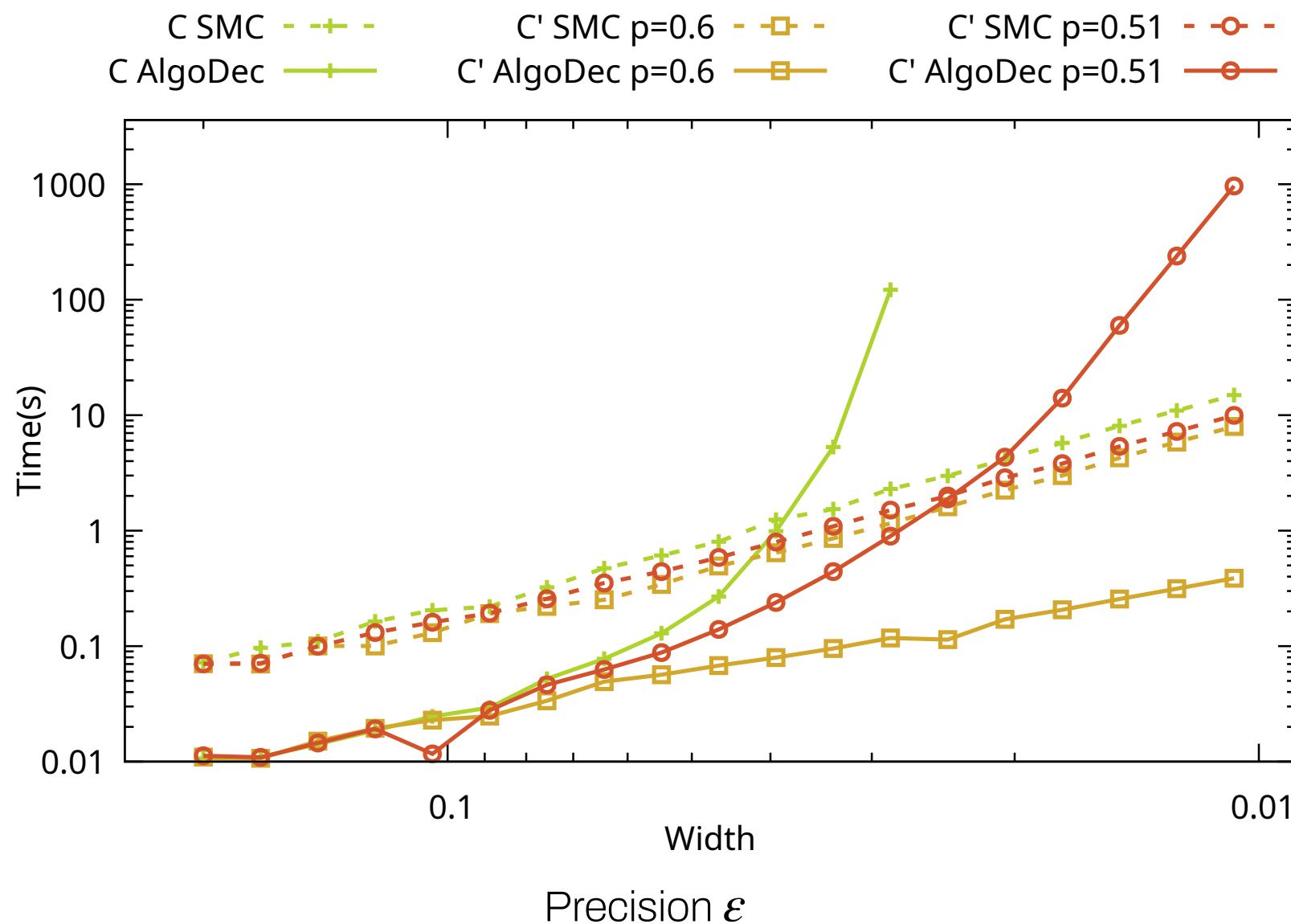
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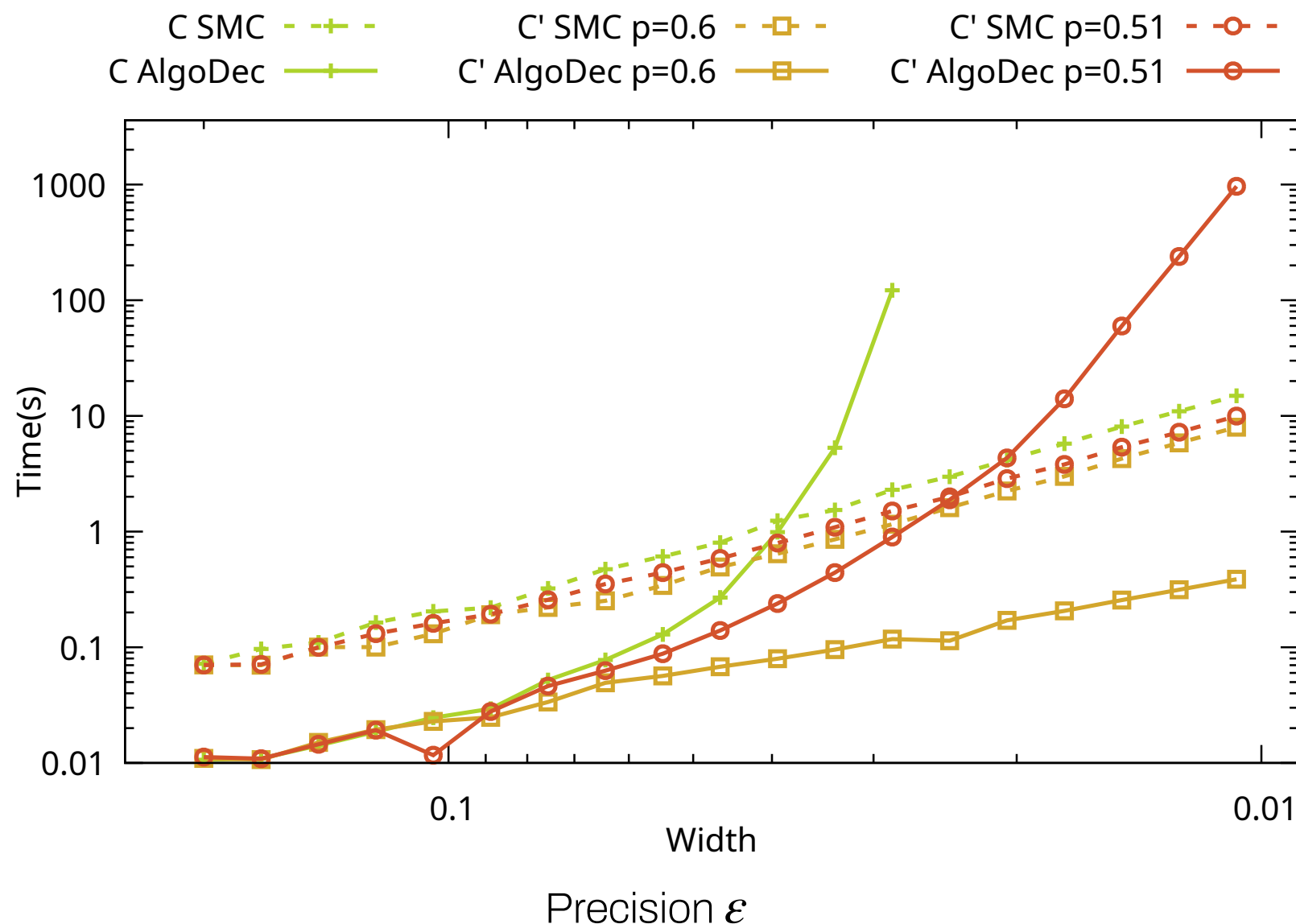
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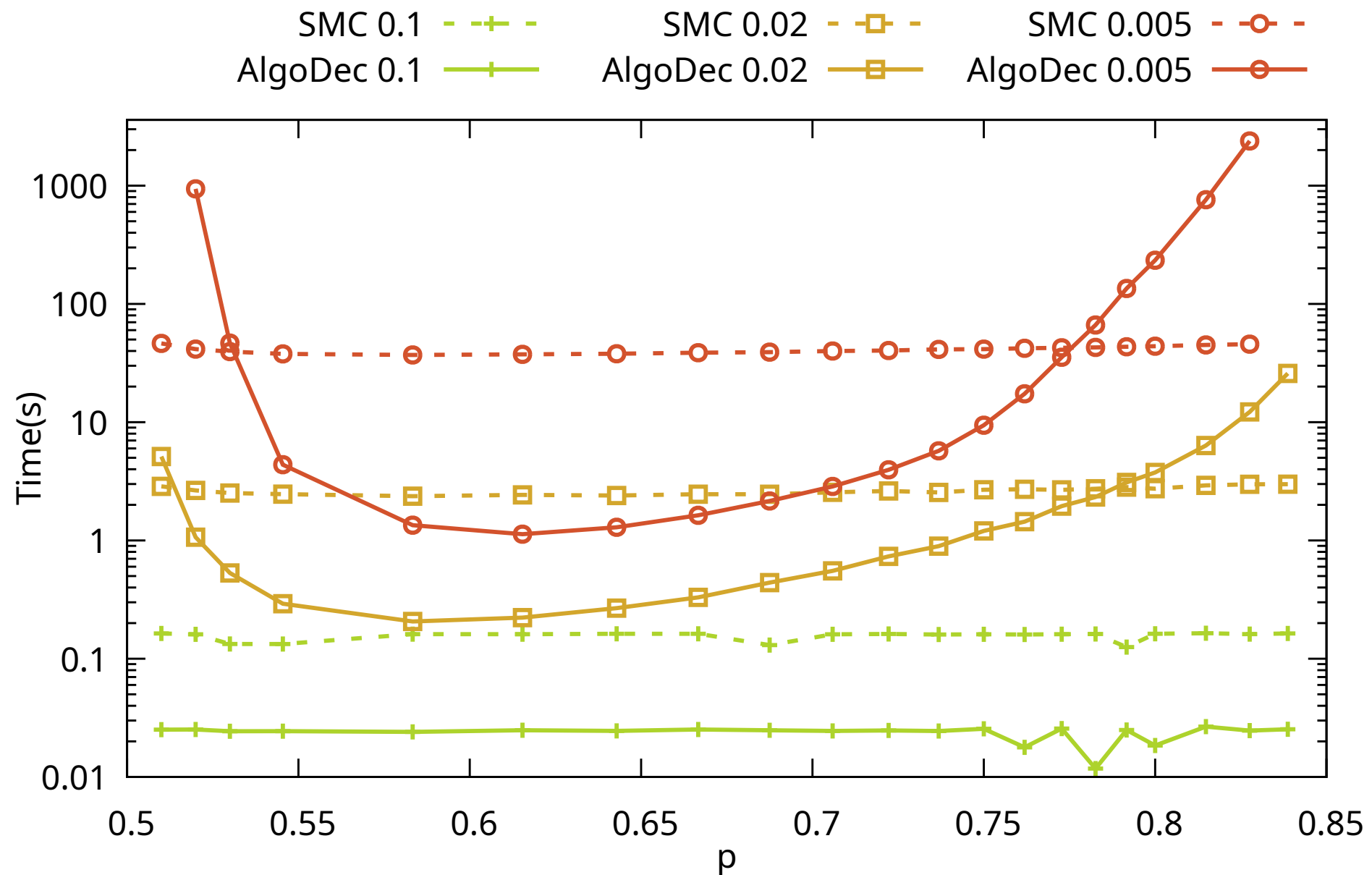
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First example — continued



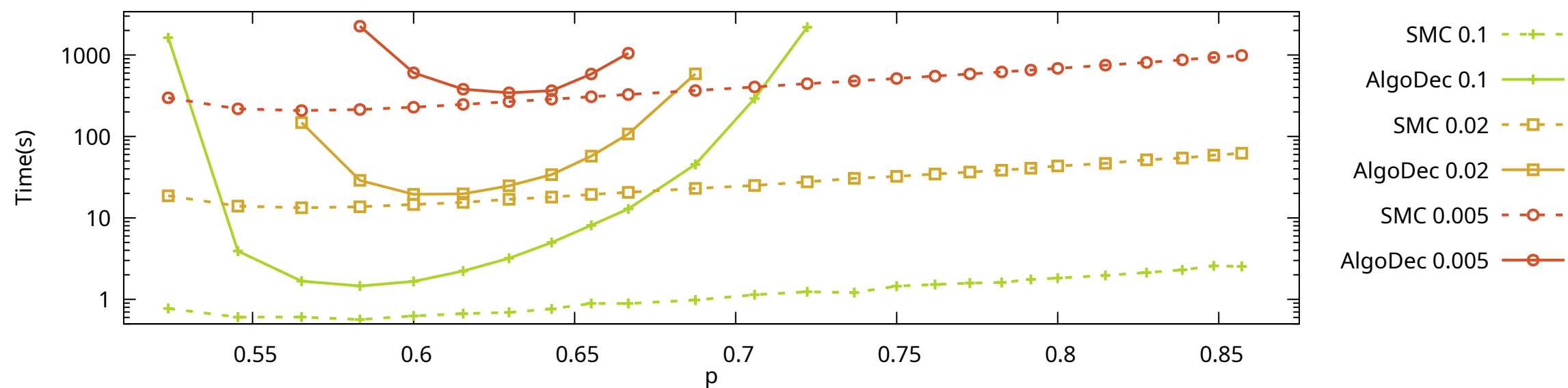
Second example

- ▶ State-free proba. pushdown automaton $\mathcal{C}$
 $A \xrightarrow{1} B \quad A \xrightarrow{1} C \quad B \xrightarrow{10} \varepsilon \quad B \xrightarrow{10+n} AA$
 $C \xrightarrow{10} A \quad C \xrightarrow{10+n} BB$
- ▶ Start from A , and target the empty stack

- ▶ It is not decisive
- ▶ It is p -divergent for every $1/2 < p < 1$

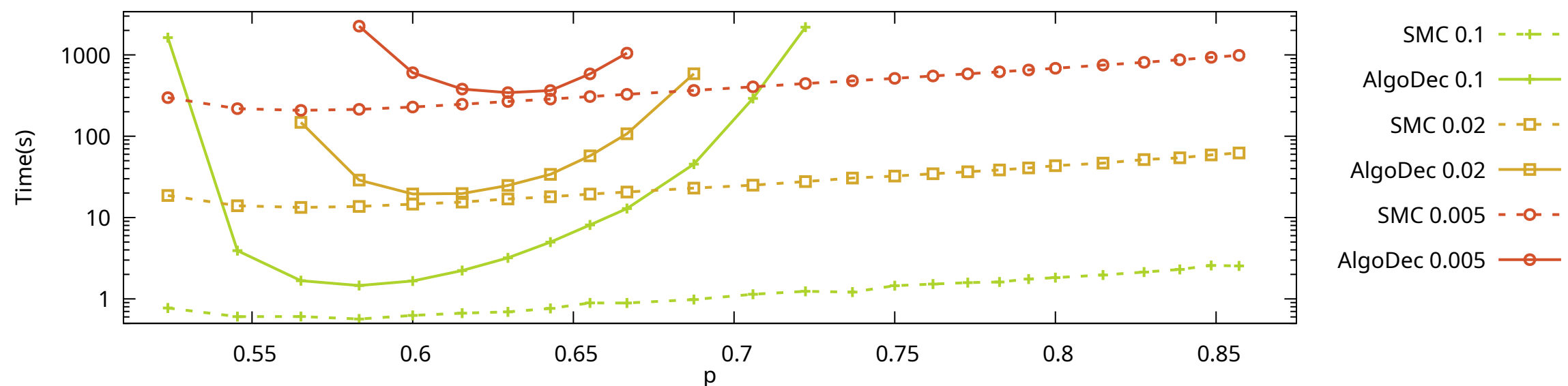
Second example

Experimental results



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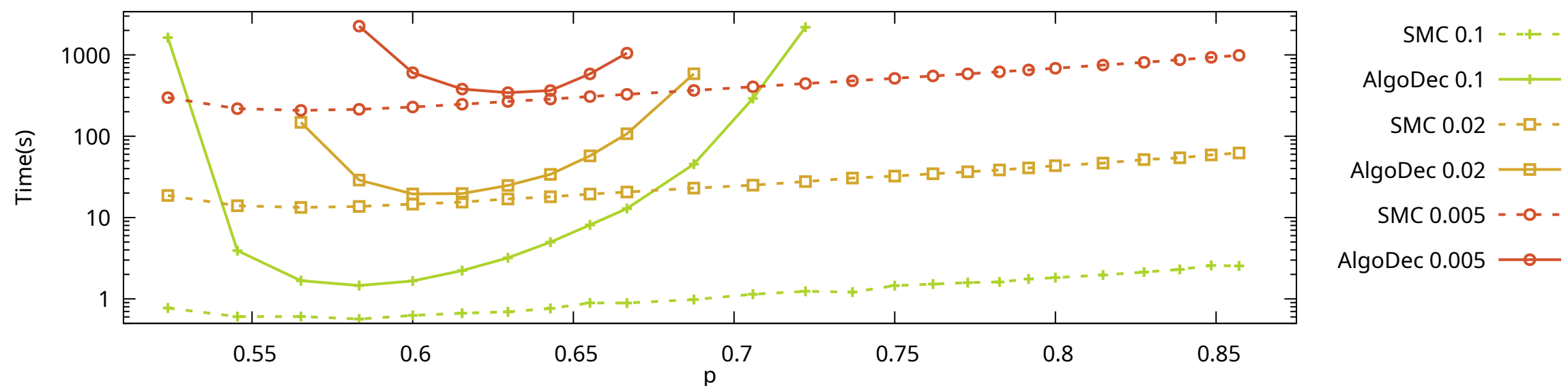
Experimental results



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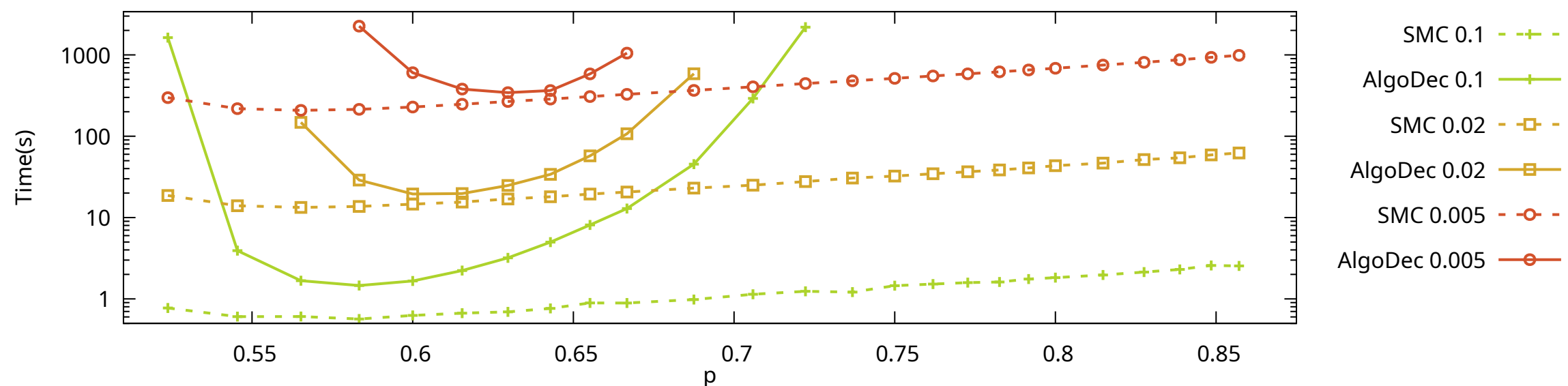
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Experimental results



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Deterministic guarantees

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Some smoother conditions for application of the approach?

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